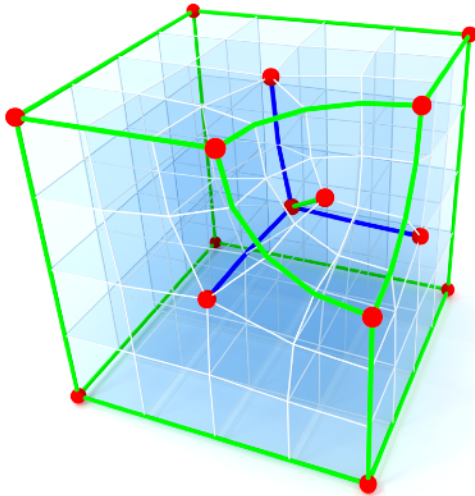


# Integer-Grid Maps for Hexahedral Mesh Generation

David Bommes  
Computer Graphics Group



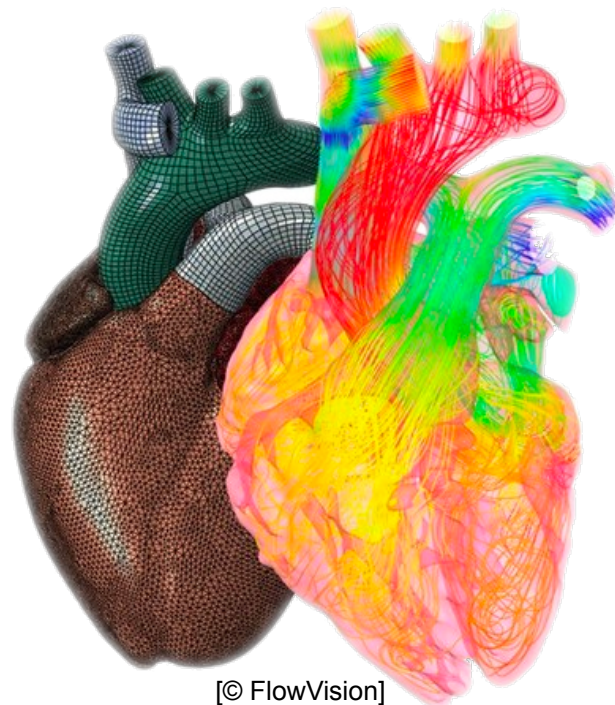
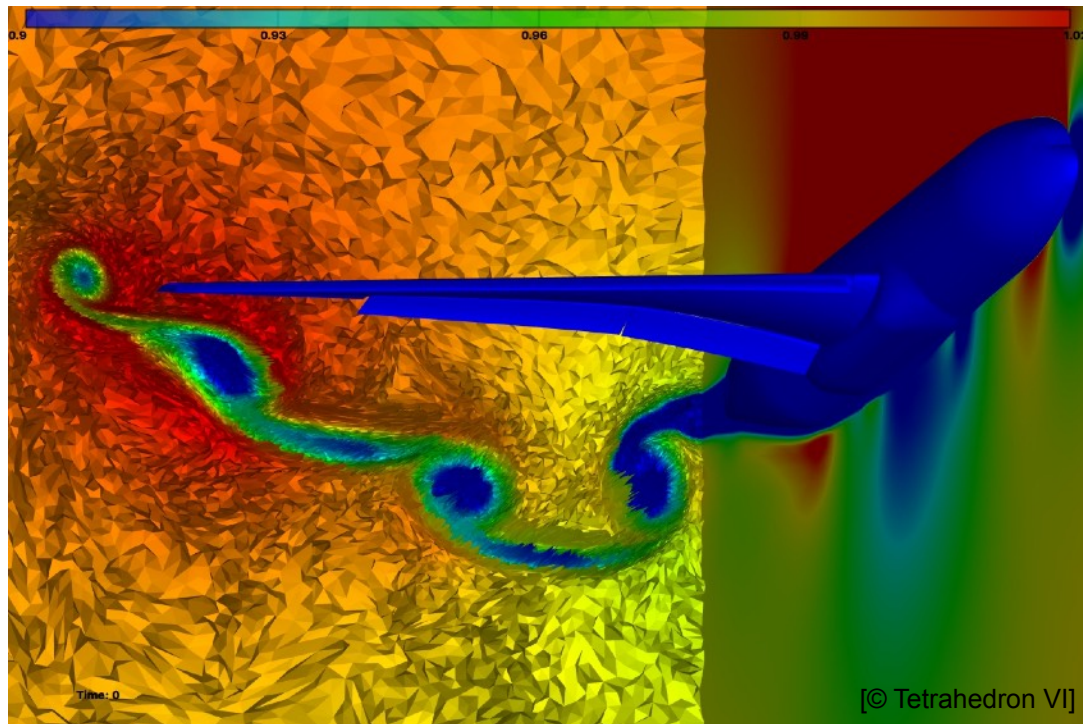
*u*<sup>b</sup>

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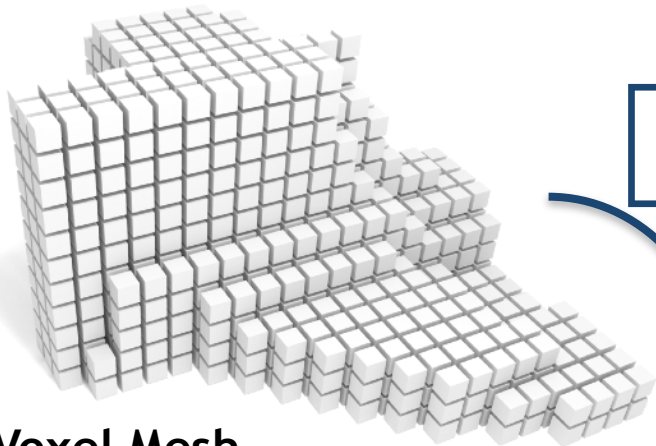
*b*  
**UNIVERSITÄT  
BERN**

# Context

# Simulation depends on Volumetric Discretization



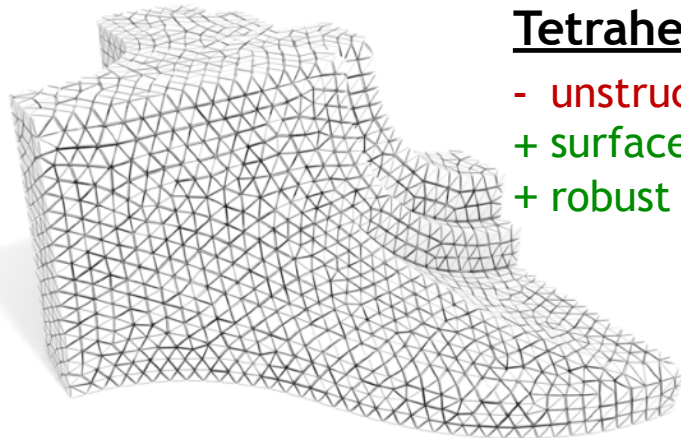
# How to discretize volumetric domains?



## Voxel Mesh

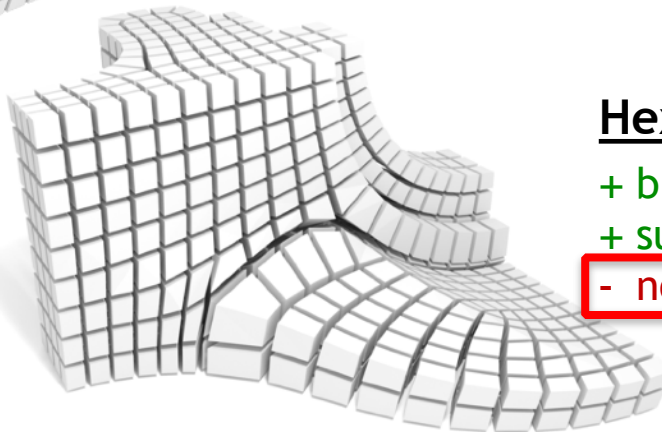
- + structured
- no surface alignment
- + trivial generation

combine strengths



## Tetrahedral Mesh

- unstructured
- + surface alignment
- + robust algorithms



## Hexahedral Mesh

- + block-structured
- + surface alignment
- no automatic algorithms

**Breakthrough required!**

# HexMeshing Challenges

# Why is Hexahedral Meshing so difficult?

- good hexahedral meshes require...

1. **approximation**

- faithful boundaries & internal structures

2. **complexity**

- low number of elements

3. **regularity**

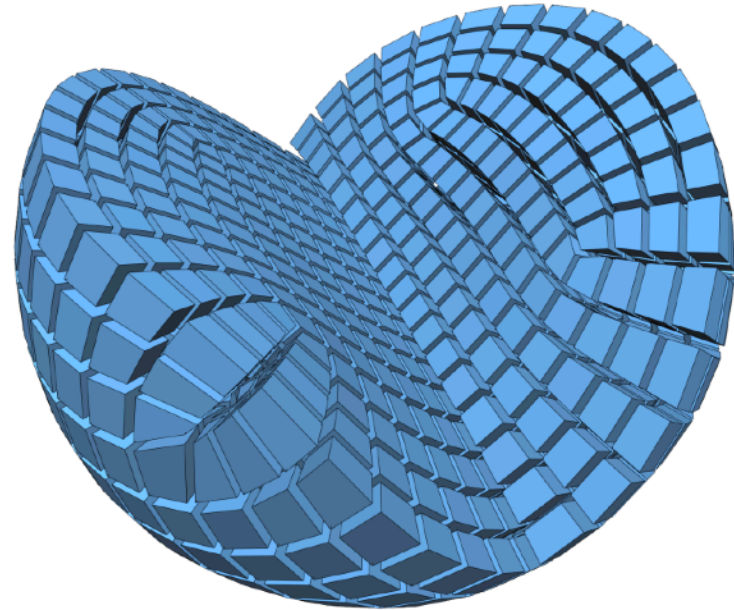
- few singularities/irregularities

4. **element quality**

- low geometric distortion

5. **anisotropy and sizing**

- application dependent



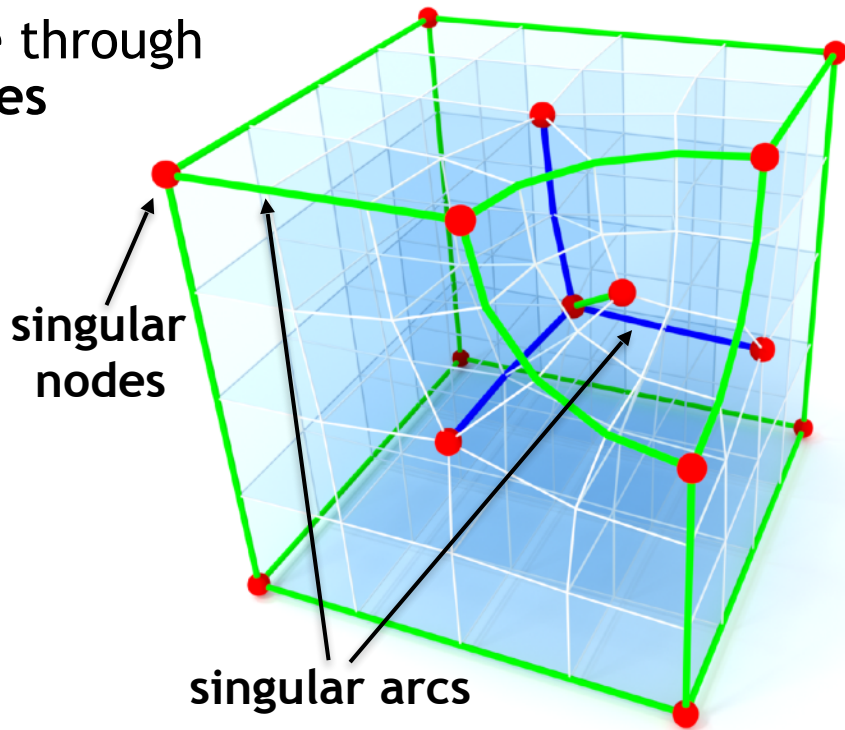
## **conflicting objectives**

- existing algorithms optimize only subset
- need holistic approach

# Why is Hexahedral Meshing so difficult?

- **Key observation:**  
good block-structure only possible through  
global optimization of singularities

**State of the art:**  
Manual decomposition  
into simple parts



# Integer-Grid Maps Approach



# A new approach for an old problem

**Main Principle:** View hex mesh generation as a **holistic** optimization problem and apply **global optimization**

## Simultaneously Optimize

1. approximation
2. complexity
3. regularity
4. element quality
5. anisotropy & sizing

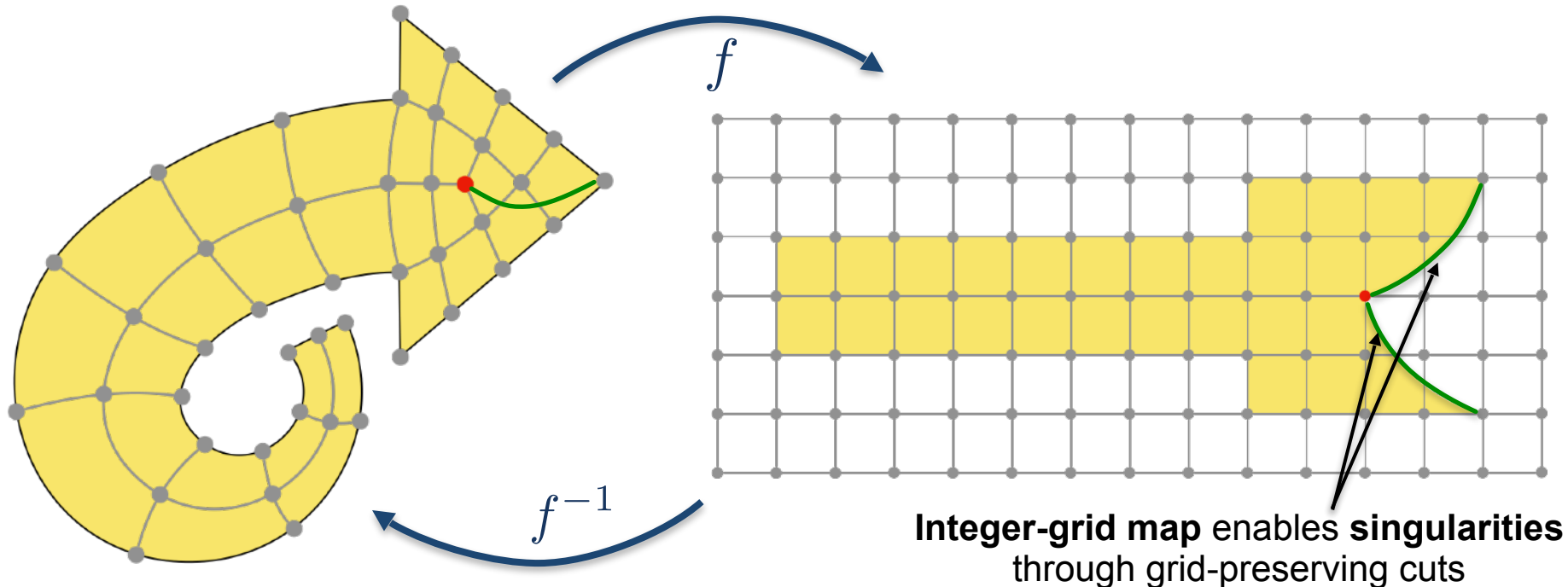
**Problem:** naïve formulation gives practically infeasible large-scale non-convex mixed-integer problem

## Key to Success

1. Suitable parametrization of the problem
2. Scalable and **global** optimization strategy

# Suitable Parametrization of the Problem

Idea: Interpret Mesh Generation as Map Optimization



# Suitable Parametrization of the Problem

Idea: Interpret Mesh Generation as Map Optimization

## Optimize Mesh

1. approximation
2. complexity
3. regularity
4. element quality
5. anisotropy & sizing

**highly discrete**

translates into

## Optimize Map

1. alignment of map
2. grid volume
3. map distortion
4. map distortion
5. metric of map

translates into

## Variational

$$E(f) \rightarrow \min$$

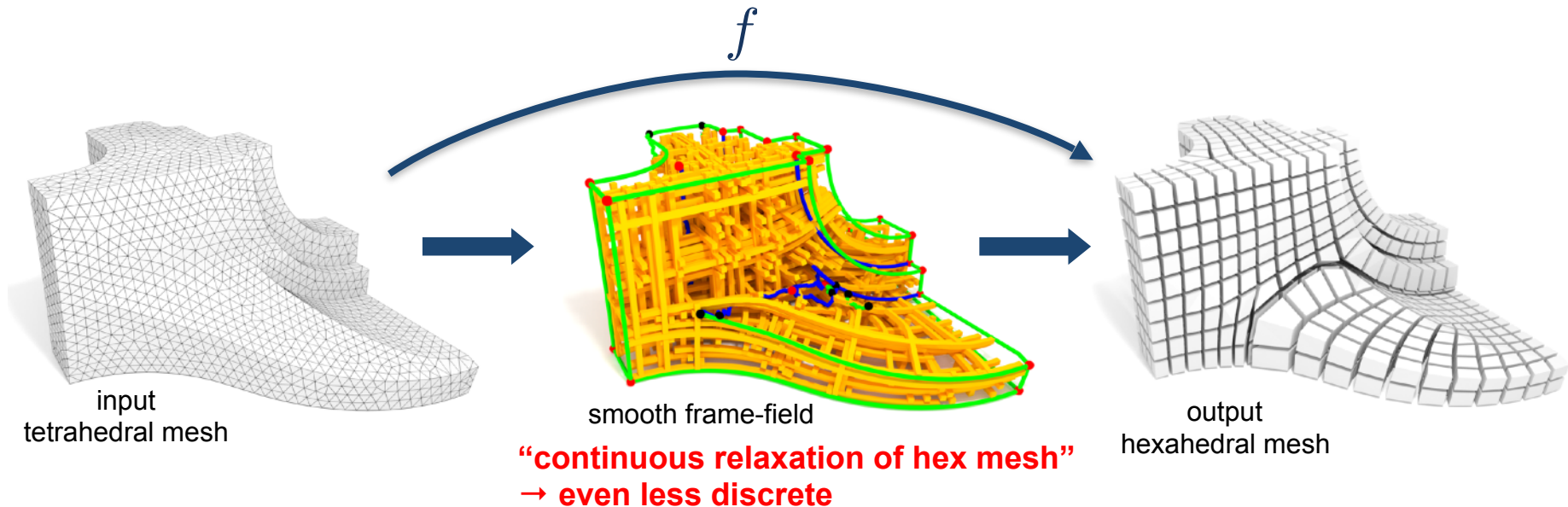
Mixed-Integer  
Problem

**less discrete since  
elements implicit in map**

# Scalable and Global Optimization Strategy

**Problem:** Mixed-Integer Problem  $E(f) \rightarrow \min$  **still too difficult**

**Idea:** Decouple into series of (geometrically motivated) relaxations



# State of the Art

## Quad Meshing with IGMs

# Success Story of Integer-Grid Maps in Quad Meshing

## Technology Transfer based on

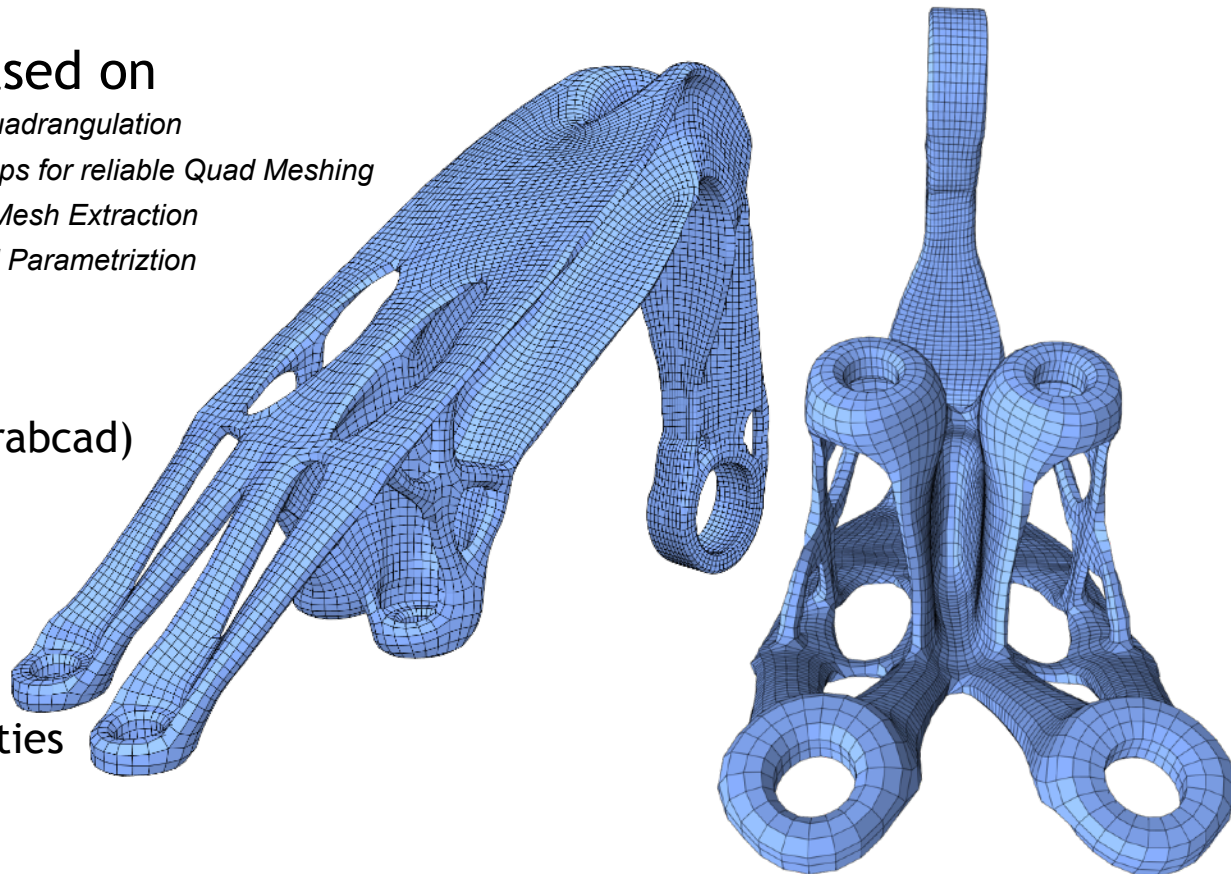
- [Bommes et al. 2009] – *Mixed-Integer Quadrangulation*
- [Bommes et al. 2013a] – *Integer-Grid Maps for reliable Quad Meshing*
- [Ebke et al. 2013] – *QEX: Robust Quad Mesh Extraction*
- [Campen et al. 2015] – *Quantized Global Parametrization*

## Example Model:

- airplane bearing bracket (grabcad)
- #triangles = 215k
- genus = 19

## Output:

- one-click solution
- globally optimized singularities
- runtime **80s** (#quads = 17k)



# Success Story of Integer-Grid Maps in Quad Meshing

## Technology Transfer based on

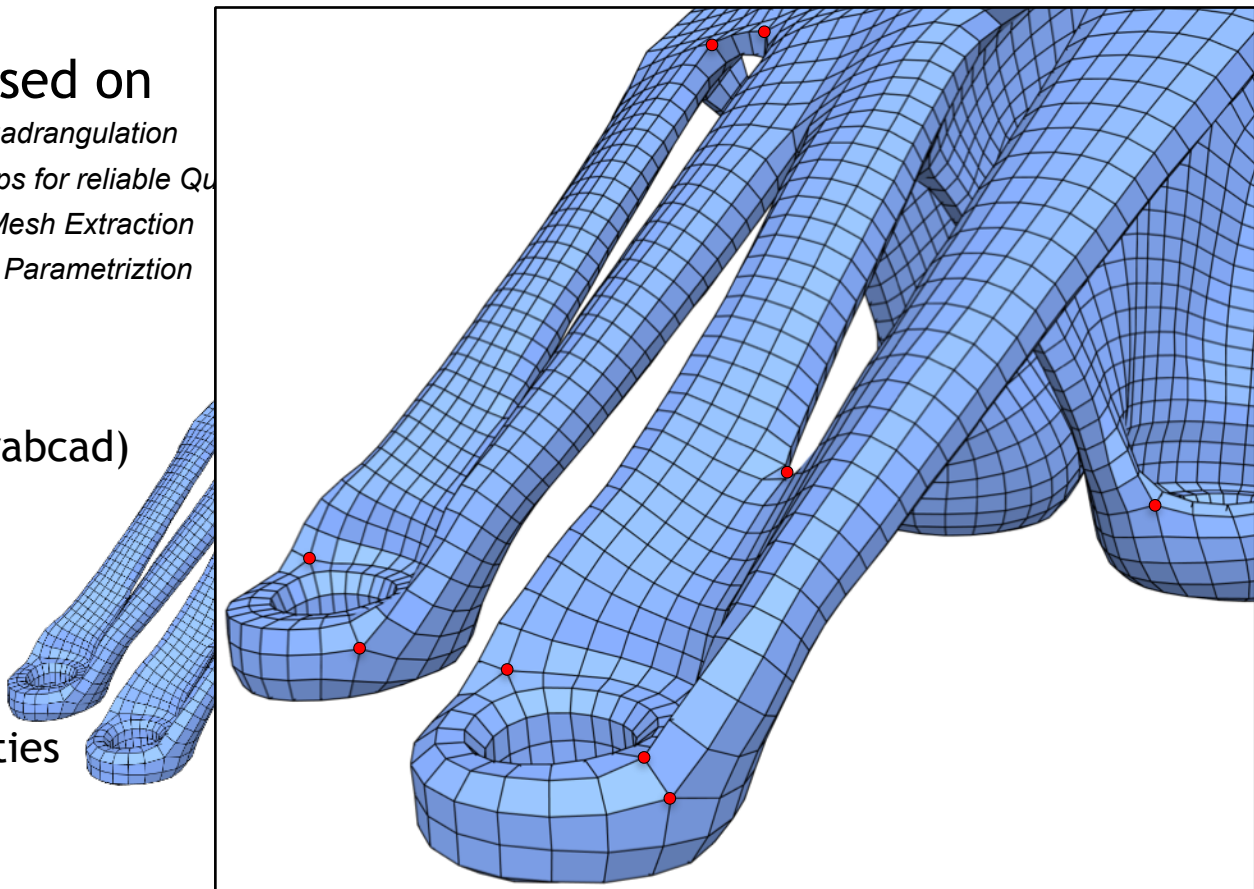
- [Bommes et al. 2009] – *Mixed-Integer Quadrangulation*
- [Bommes et al. 2013a] – *Integer-Grid Maps for reliable Quad Meshing*
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## Example Model:

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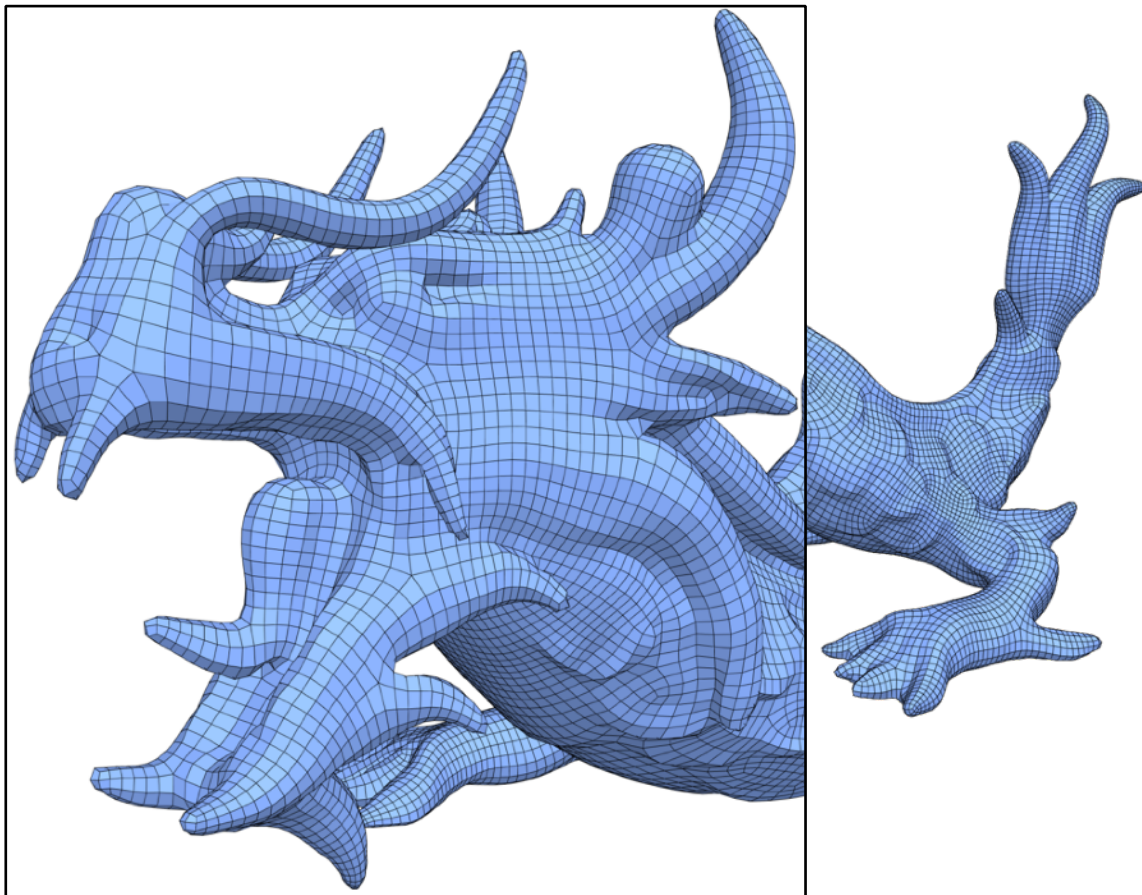
## Output:

- one-click solution
- globally optimized singularities
- runtime **80s** (#quads = 17k)



# Results — one-click solution

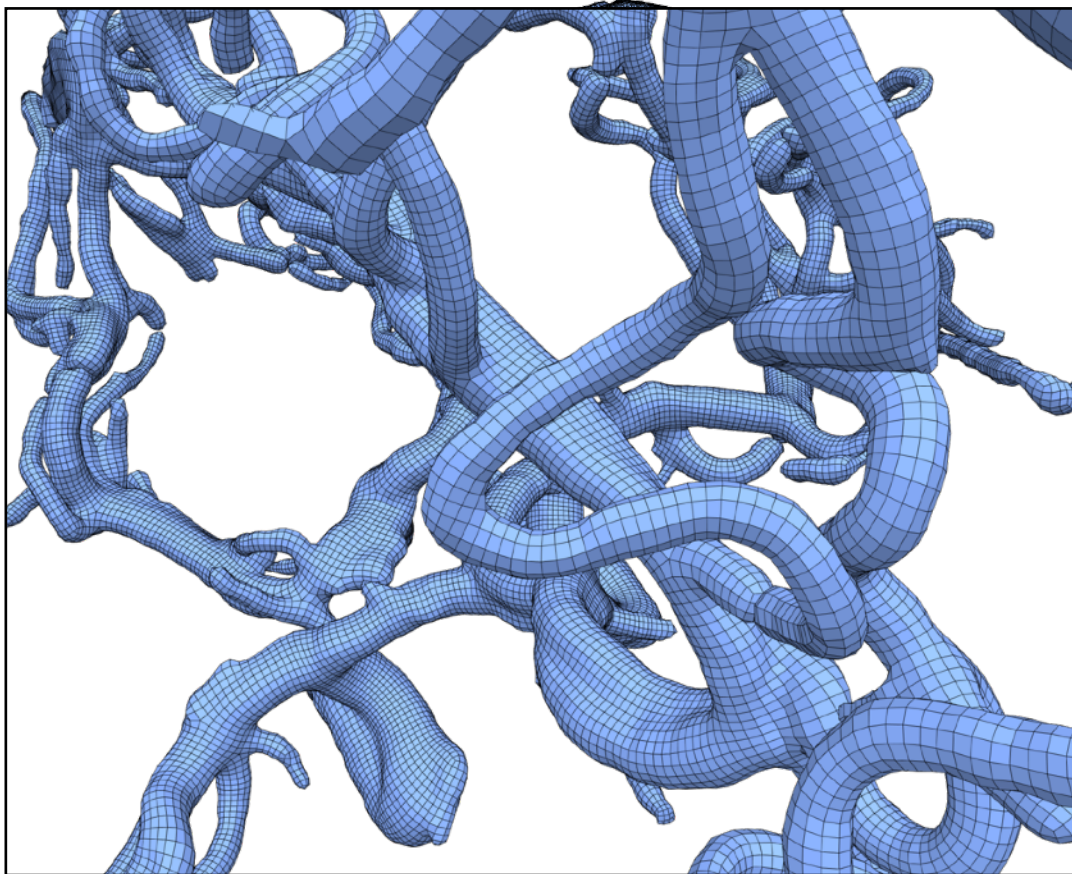
- asian dragon
- **input:**
  - #triangles 140k
  - many geometric details
- **output:**
  - #singularities 624
  - #quads 27k
  - runtime **90s**



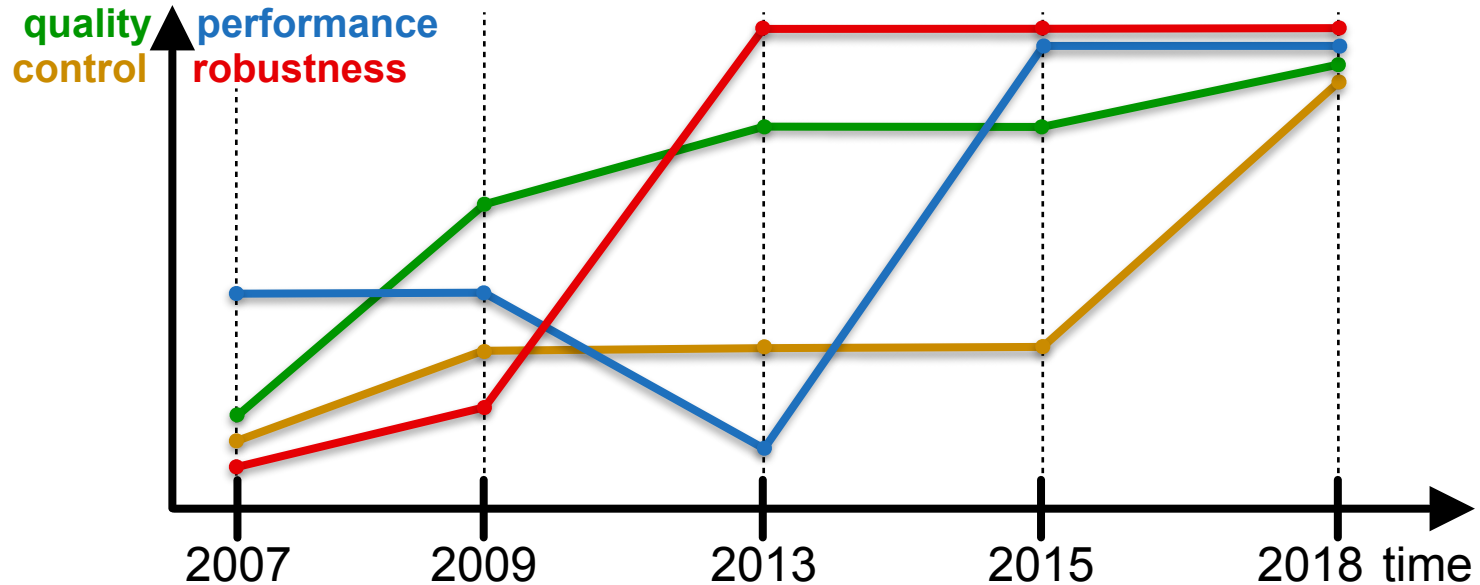


# Results — one-click solution

- vascular structure
- **input:**
  - #triangles 224k
  - tubular network
- **output:**
  - #singularities 1851
  - #quads 125k
  - runtime **3.8min**



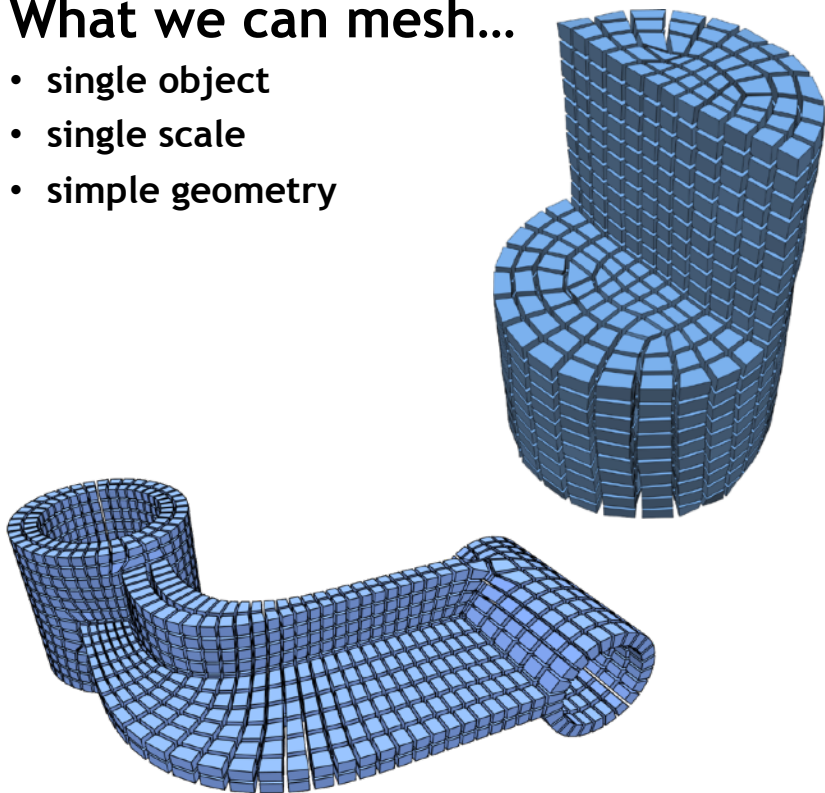
# Evolution of Integer-Grid Map Algorithms



# State of the Art – Hexahedral Meshing with IGMs

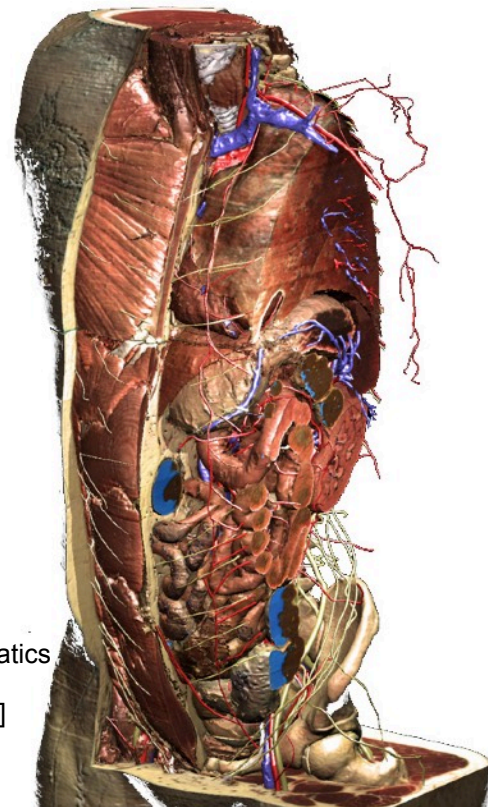
## What we can mesh...

- single object
- single scale
- simple geometry



## What we would like to mesh ...

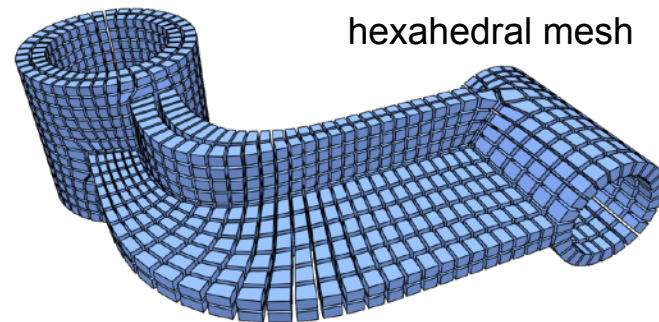
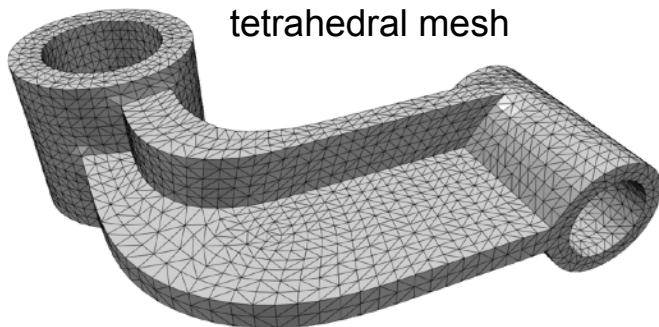
- nested objects
- multiple scales
- complex geometry



[© Institute of Mathematics  
and CS in Medicine -  
University of Hamburg]

# Hexahedral Meshing via Integer-Grid Maps

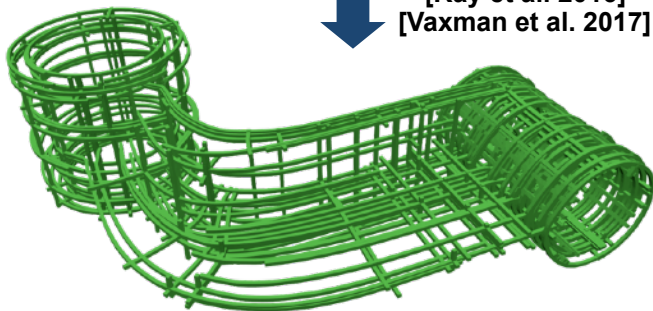
# Hexahedral Meshing via IGM



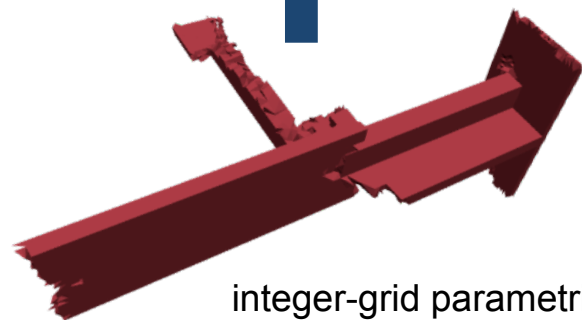
**problematic step**



[Huang et al. 2011]  
[Li et al. 2012]  
[Jiang et al. 2014]  
[Ray et al. 2016]  
[Vaxman et al. 2017]



[Lyon et al. 2016]



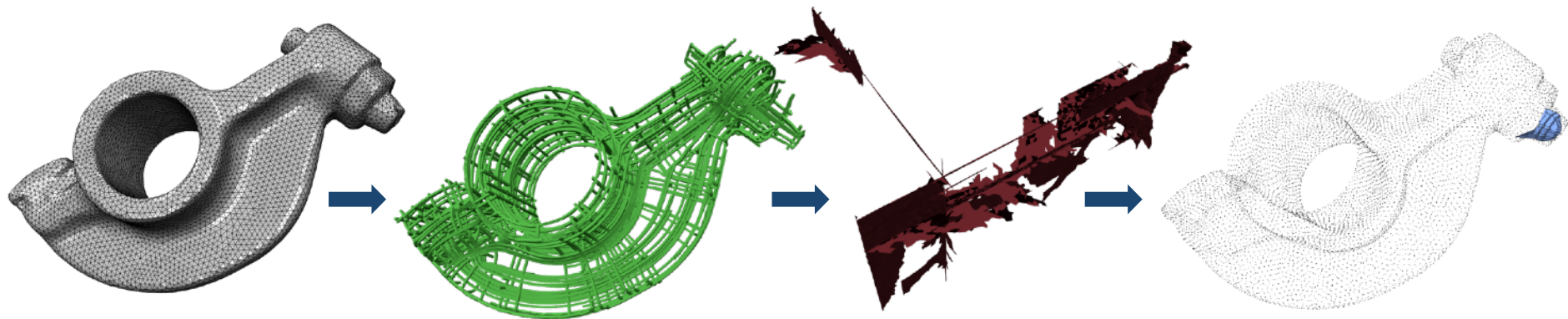
# Fundamental Topological Problem

hexahedral mesh  
singularities



frame-field  
singularities

invalid singularities  
→ integer-grid map  
degenerates



# Singularity-Constrained Octahedral Fields for Hexahedral Meshing

[Liu, Zhang, Chien, Solomon, Bommes — ACM Siggraph 2018]



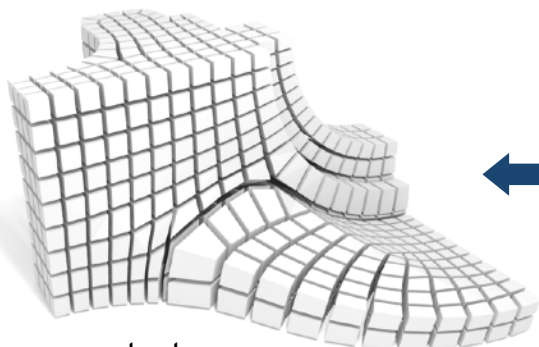
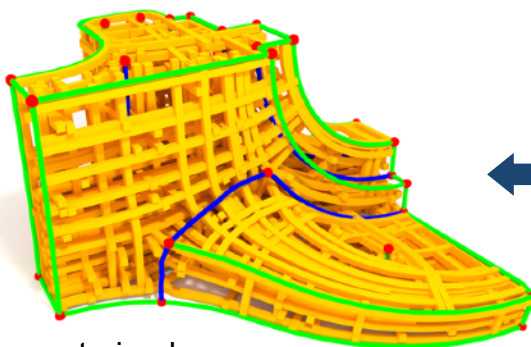
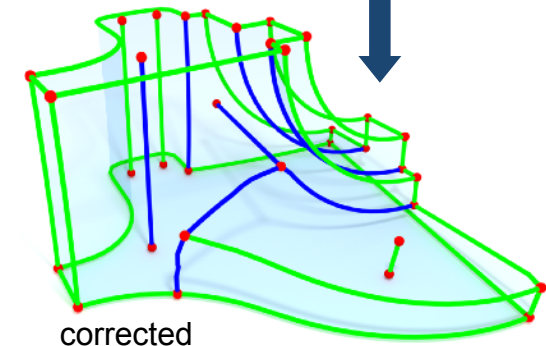
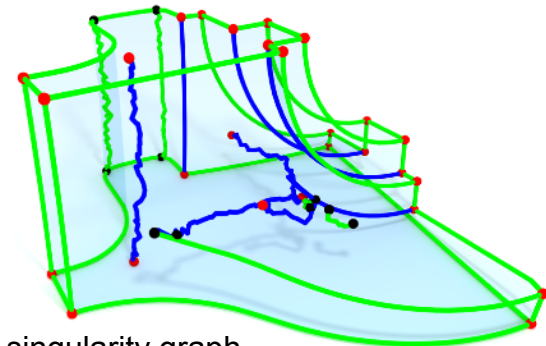
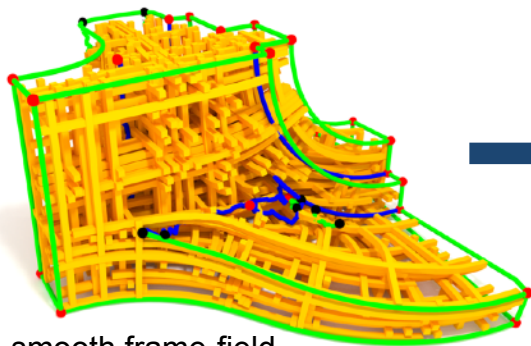
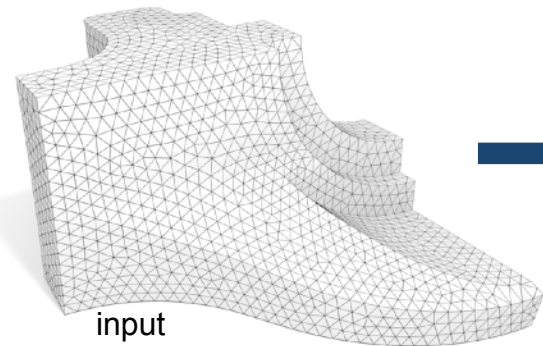
**RWTH**AACHEN  
UNIVERSITY

Visual Computing Institute



**Massachusetts  
Institute of  
Technology**

# Modified Algorithm

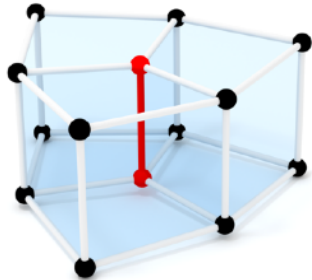




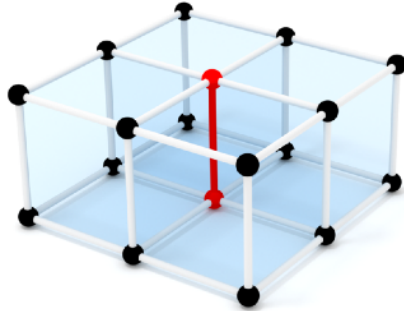
# Hex-Meshable Singularity Graphs?

# Hexahedral Mesh Singularities

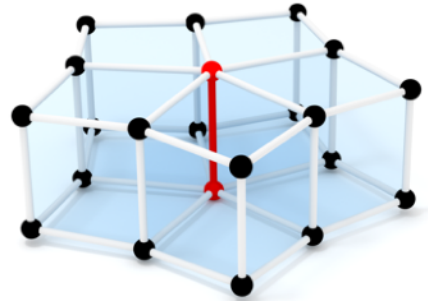
- Hexahedral mesh edges



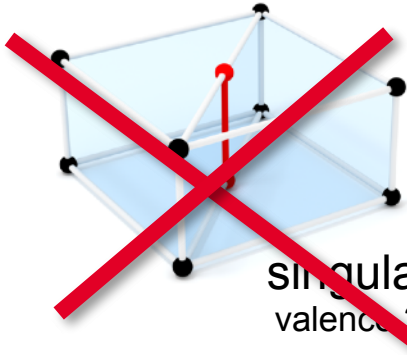
singular  
valence 3



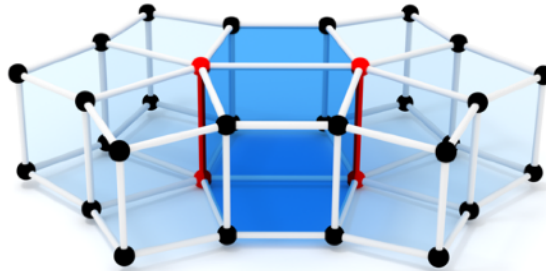
regular  
valence 4



singular  
valence 5

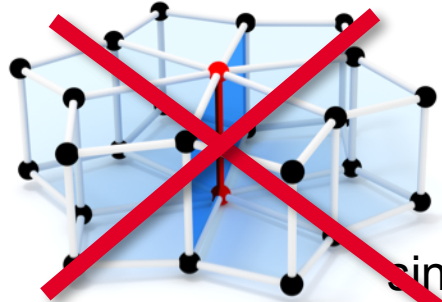


singular  
valence 2



twice valence 5

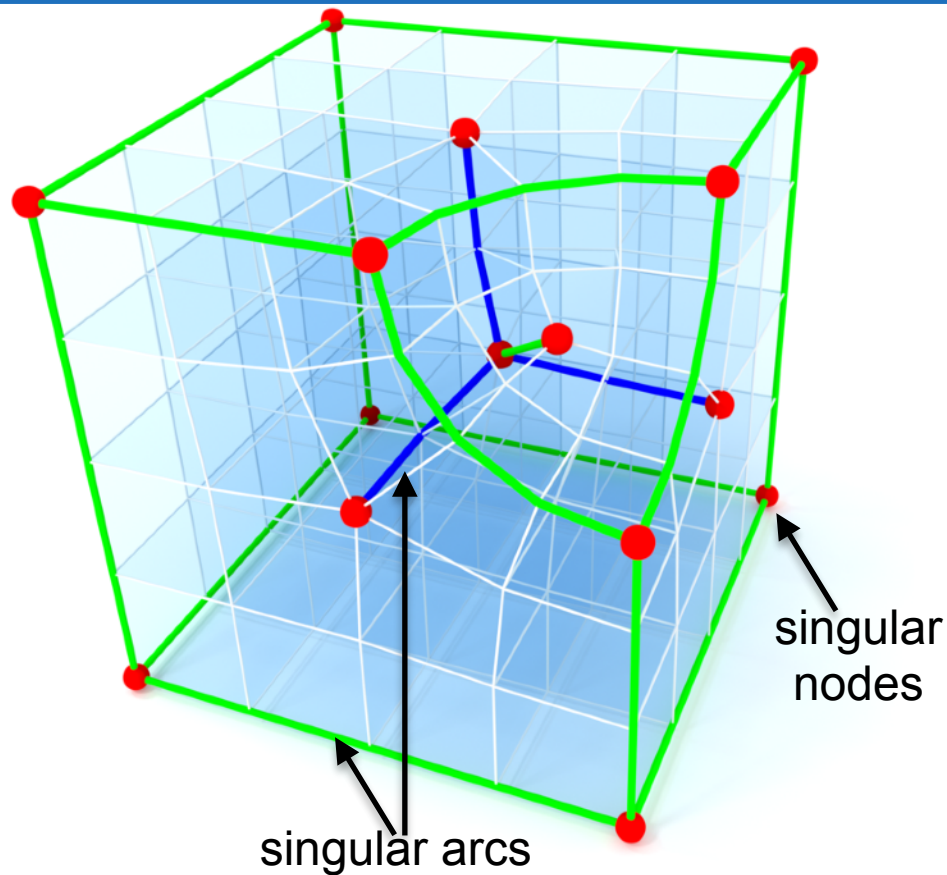
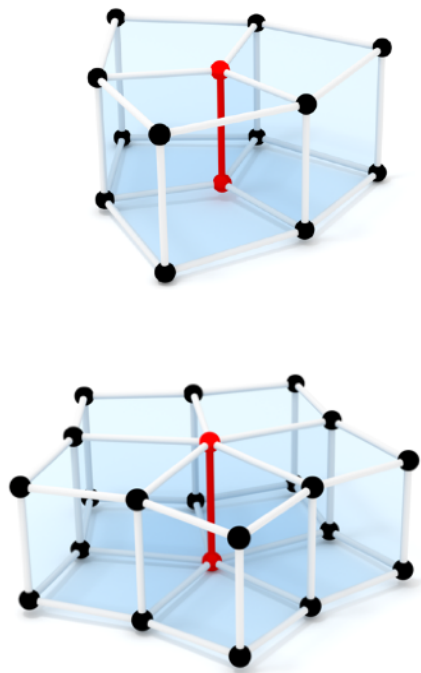
← split



singular  
valence 6

# Hexahedral Mesh Singularities

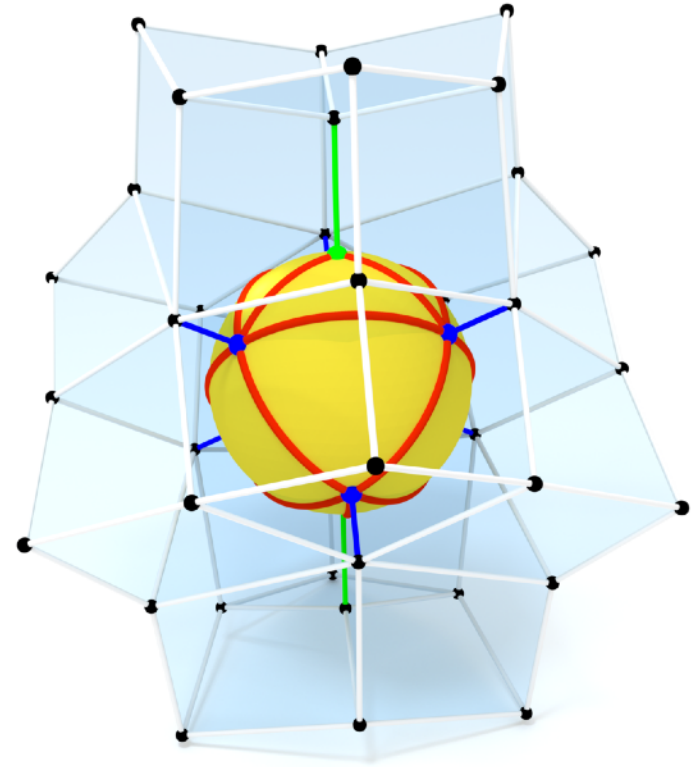
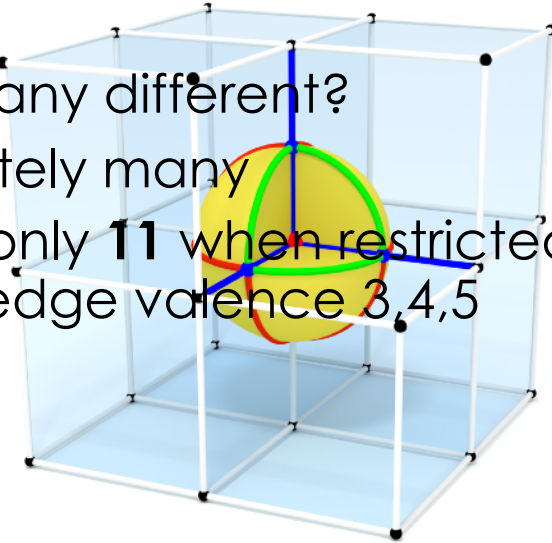
- Singularity graph



# Hexahedral Mesh Singularities

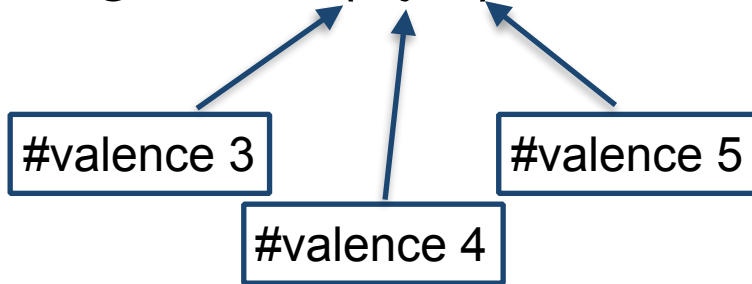
- **Observation [Nieser et al. 2011]:**  
hex mesh vertices are  
isomorphic to triangulations of  
the sphere

- How many different?
  - ➔ infinitely many
  - ➔ but only **11** when restricted to  
hex-edge valence 3,4,5



# Hexahedral Mesh Singularities

- How many sphere triangulations exists with vertex valences restricted to 3, 4, 5?
- Answer: **only 11**
- Assume triangulation has  $\#V$  vertices with signature  $(i, j, k)$



$$\text{Euler formula} \\ \#V - \#E + \#F = 2$$



$$3i + 2j + k = 12 \\ \text{with} \\ i + j + k = \#V$$

consequences:

1. minimal  $\#V = 4$  ( $i=4$ )
2. maximal  $\#V = 12$  ( $k=12$ )

# Hexahedral Mesh Singularities

$$3i + 2j + k = 12$$

with

$$i+j+k = \#V$$

- **#V=4**

(4,0,0)

valence 5 with 5 vertices requires self-connection

- **#V=5**

~~(3,1,1), (2,3,0)~~

- **#V=6**

~~(3,0,3), (2,2,2), (1,4,1), (0,6,0)~~

- **#V=7**

(0,5,2), (1,3,3), ~~(2,1,4)~~

- **#V=8**

(0,4,4), ~~(1,2,5), (2,0,6)~~

- **#V=9**

(0,3,6), ~~(1,1,7)~~

- **#V=10**

(0,2,8), ~~(1,0,9)~~

- **#V=11**

~~(0,1,10)~~

- **#V=12**

(0,0,12)

**[Schmeichel and Hakimi 1977]**

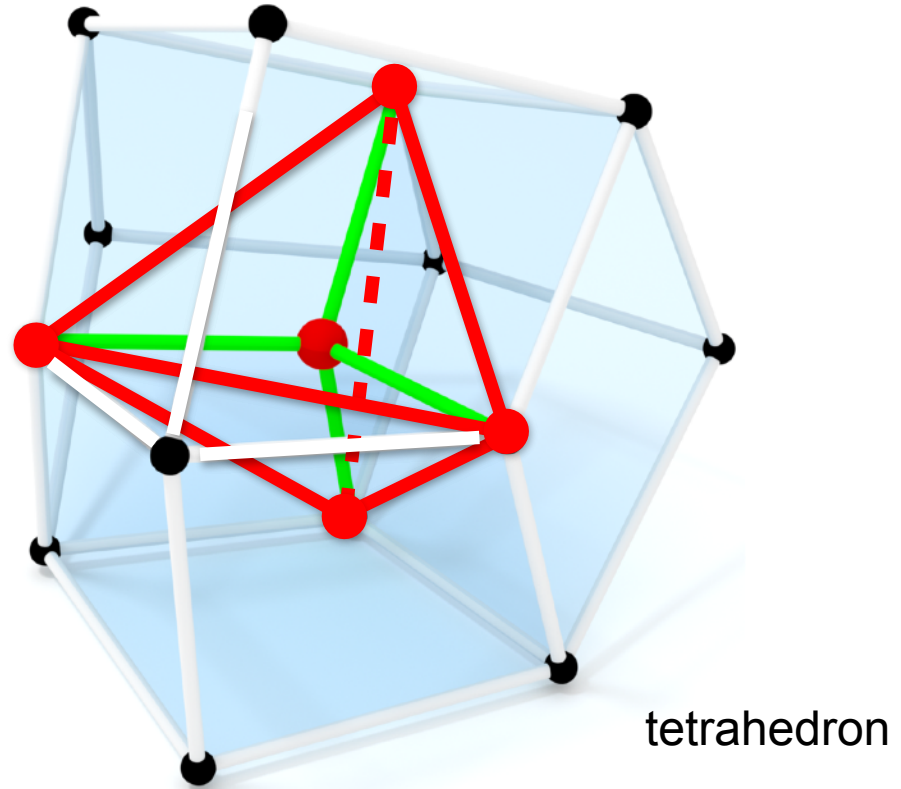
“On Planar Graphical Degree Sequences”

**[Mishra and Sarvate 2007]**

“A note on Non-Regular Planar Graphs”

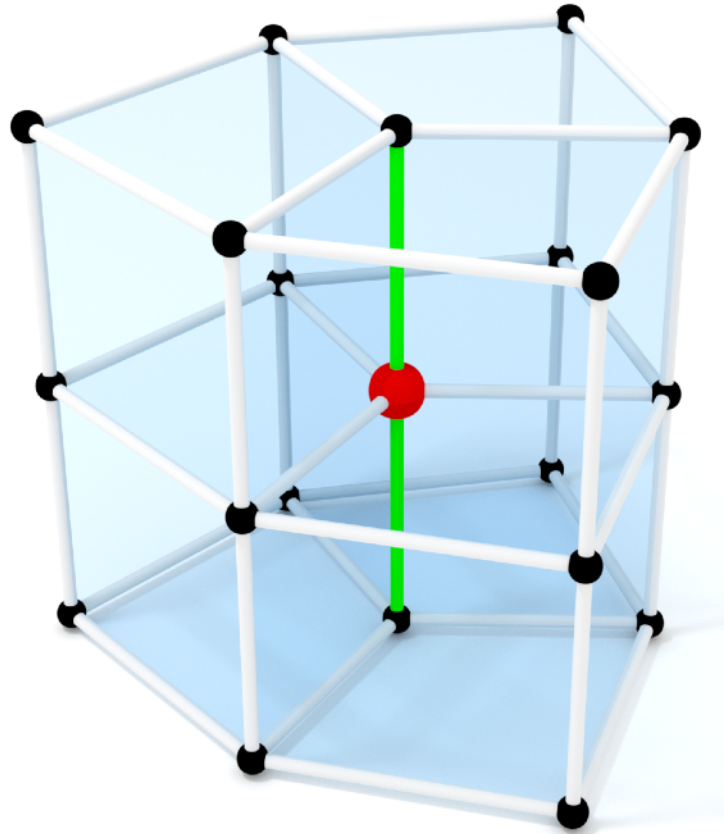
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



# Hexahedral Mesh Singularities

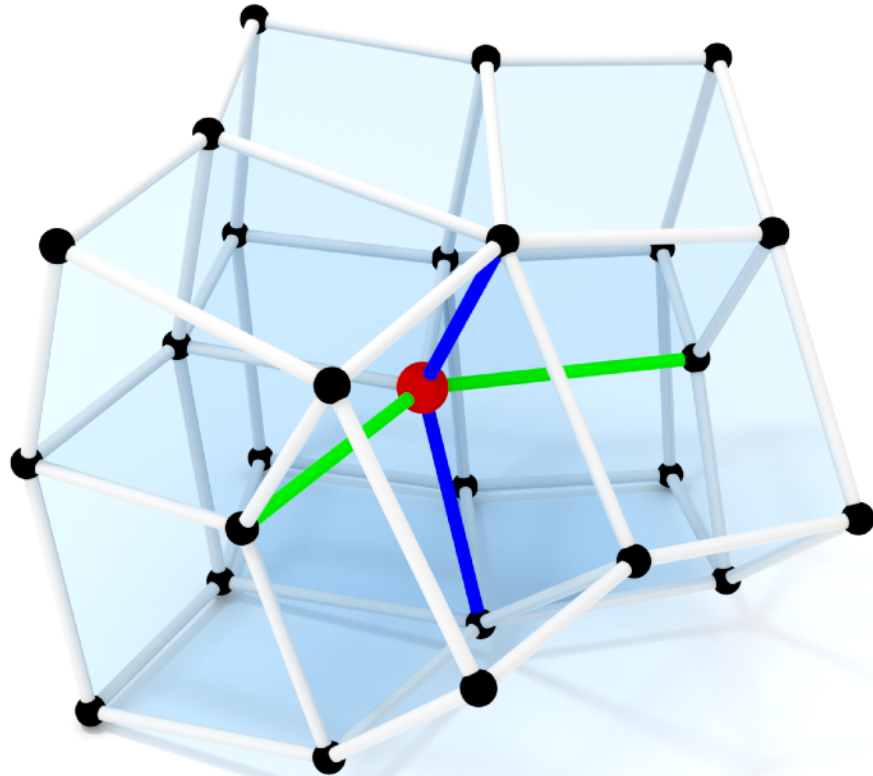
- **#V=4**  
(4,0,0)
- **#V=5**  
**(2,3,0)**
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)





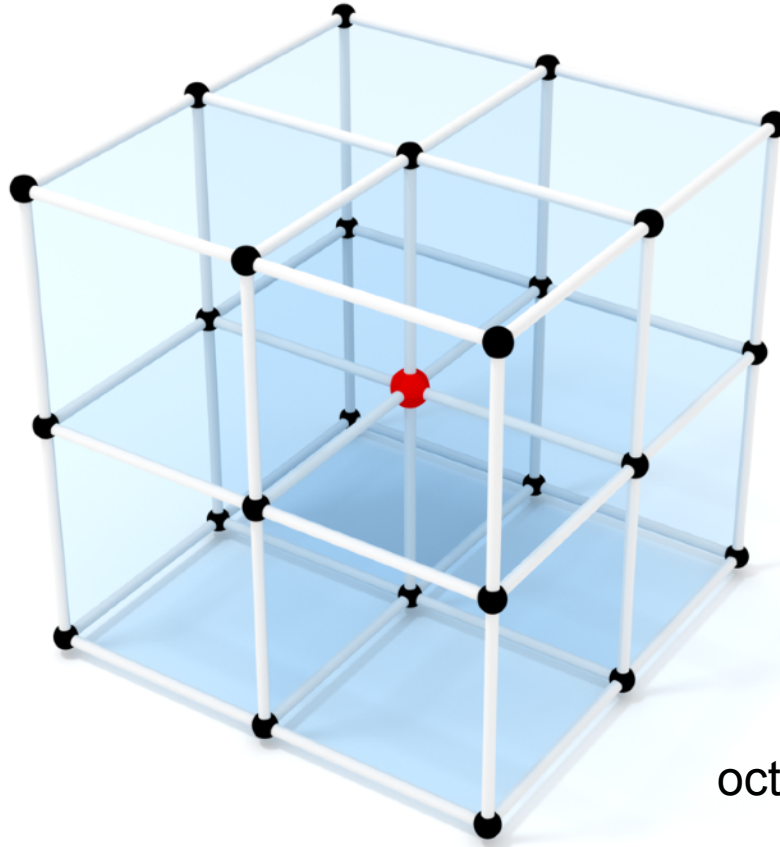
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
**(2,2,2)**, (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



# Hexahedral Mesh Singularities

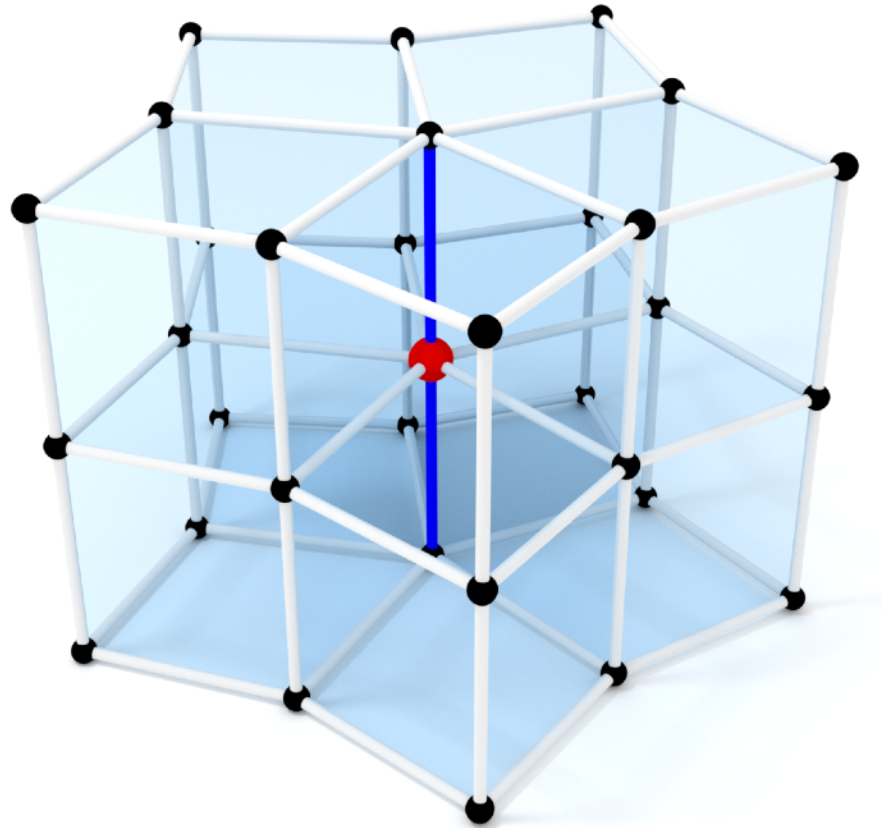
- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), **(0,6,0)**
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



octahedron

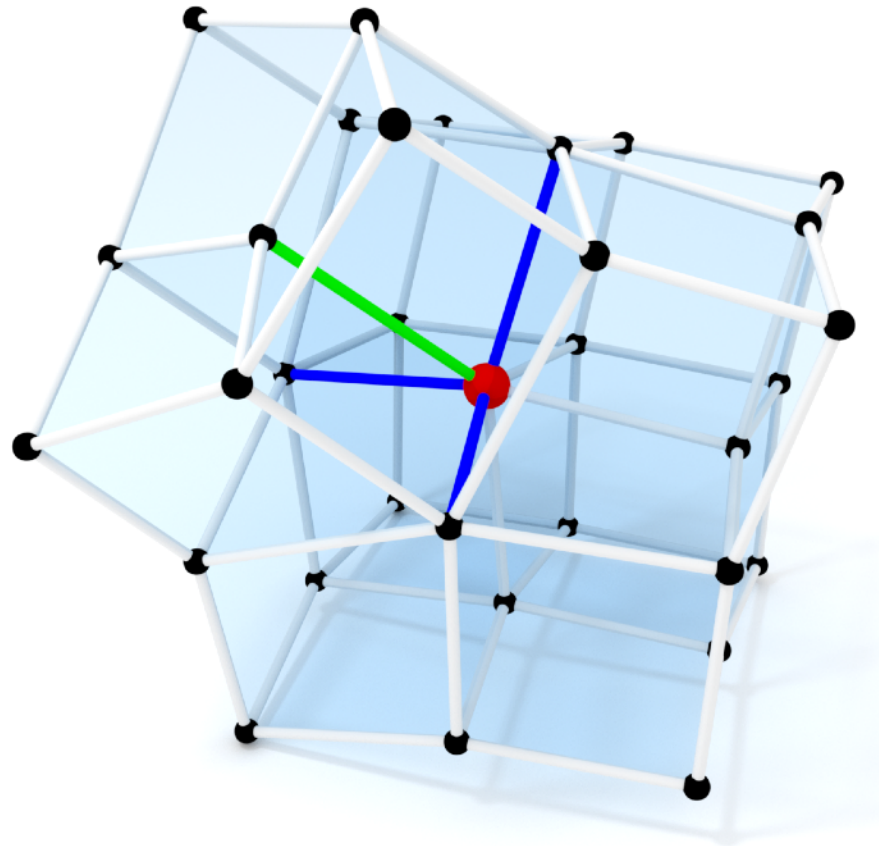
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
**(0,5,2)**, (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



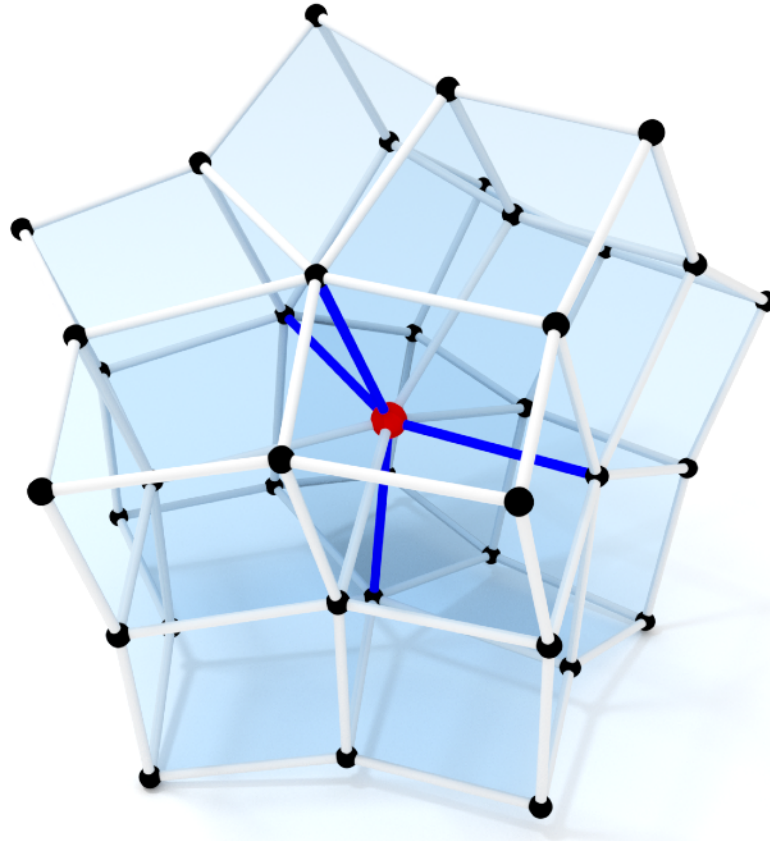
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), **(1,3,3)**
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



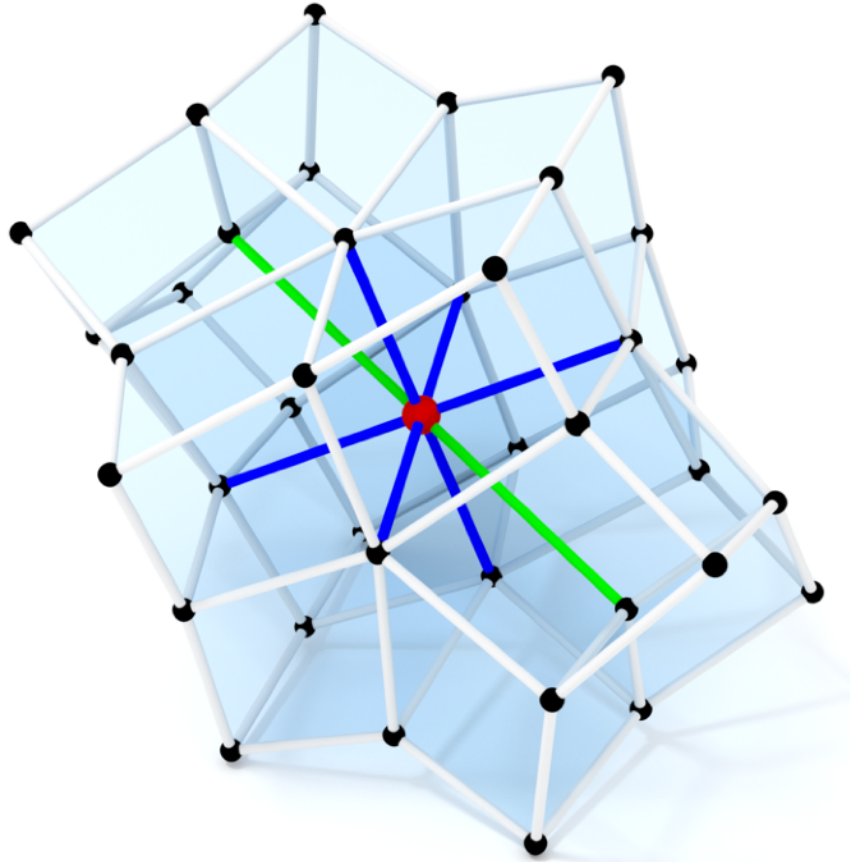
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
**(0,4,4)**, (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



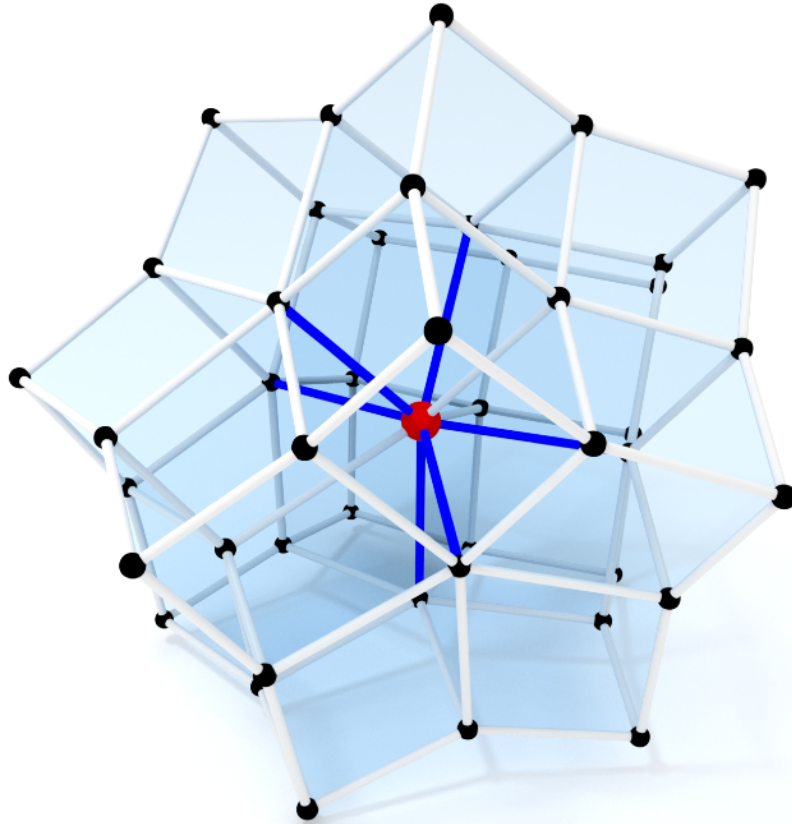
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), **(2,0,6)**
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



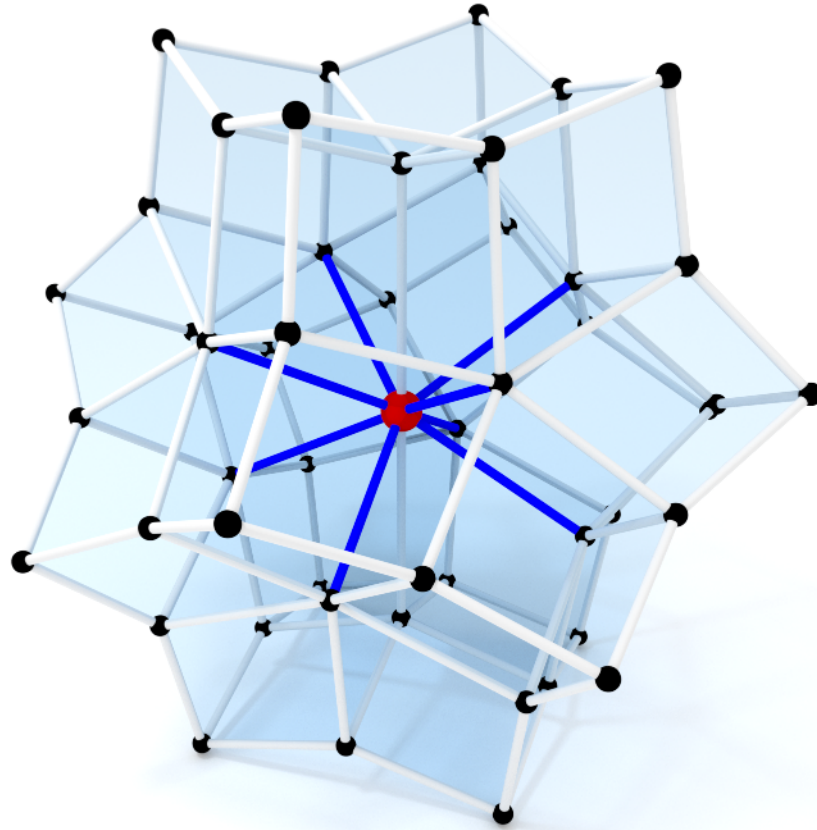
# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
**(0,3,6)**
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



# Hexahedral Mesh Singularities

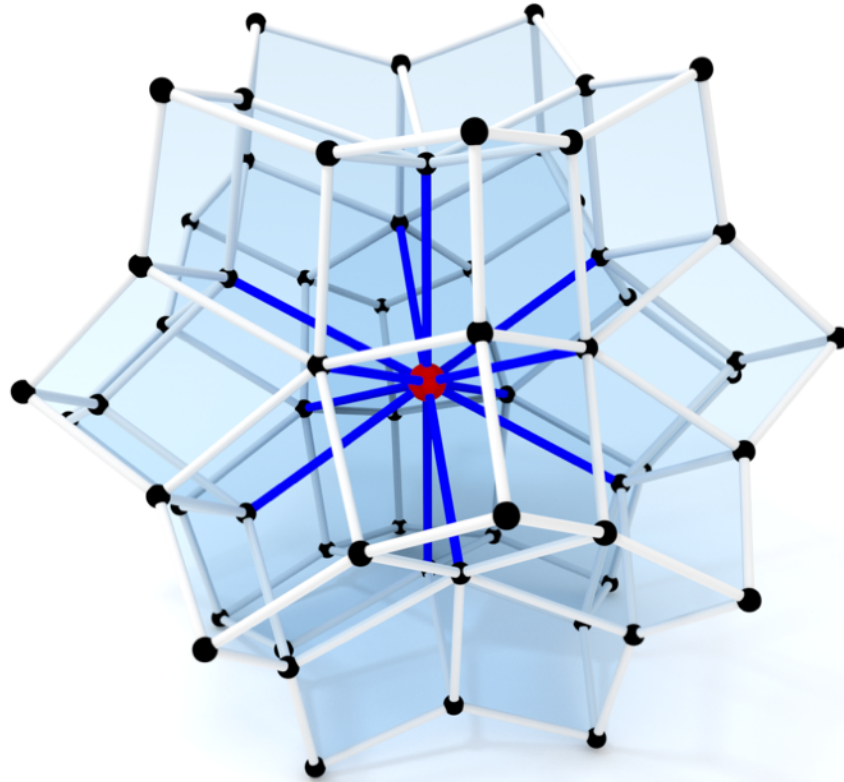
- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
**(0,2,8)**
- **#V=12**  
(0,0,12)





# Hexahedral Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
**(0,0,12)**

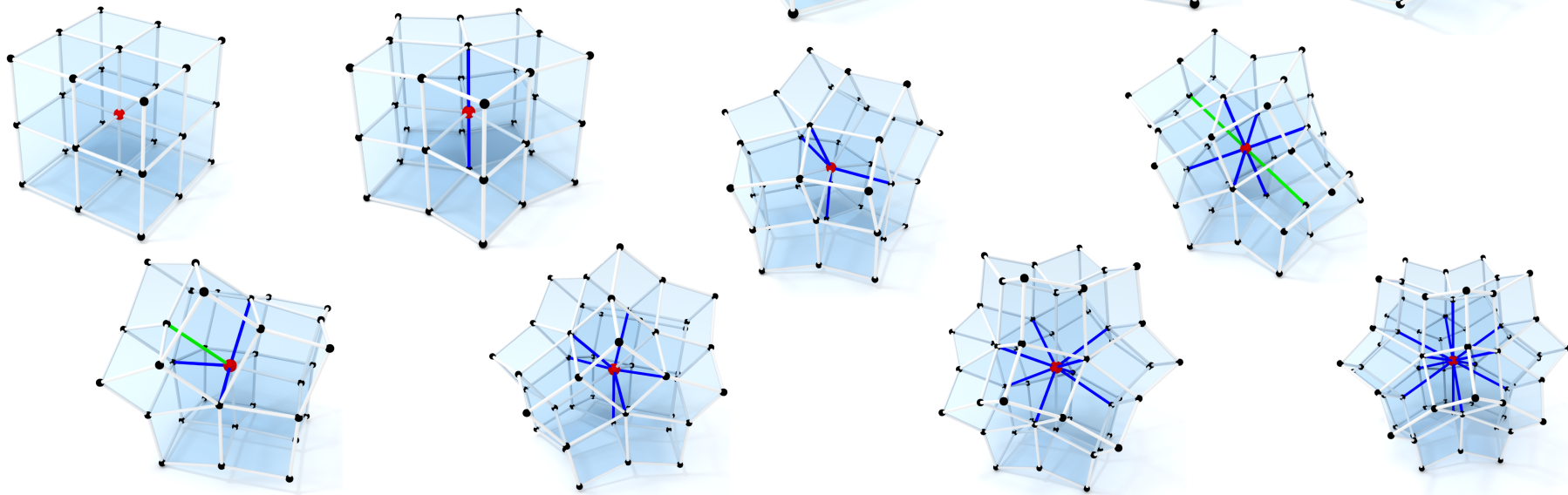


icosahedron

# Hex Meshable Singularity Graphs (valence 3/4/5)

- **Local Necessary Condition**

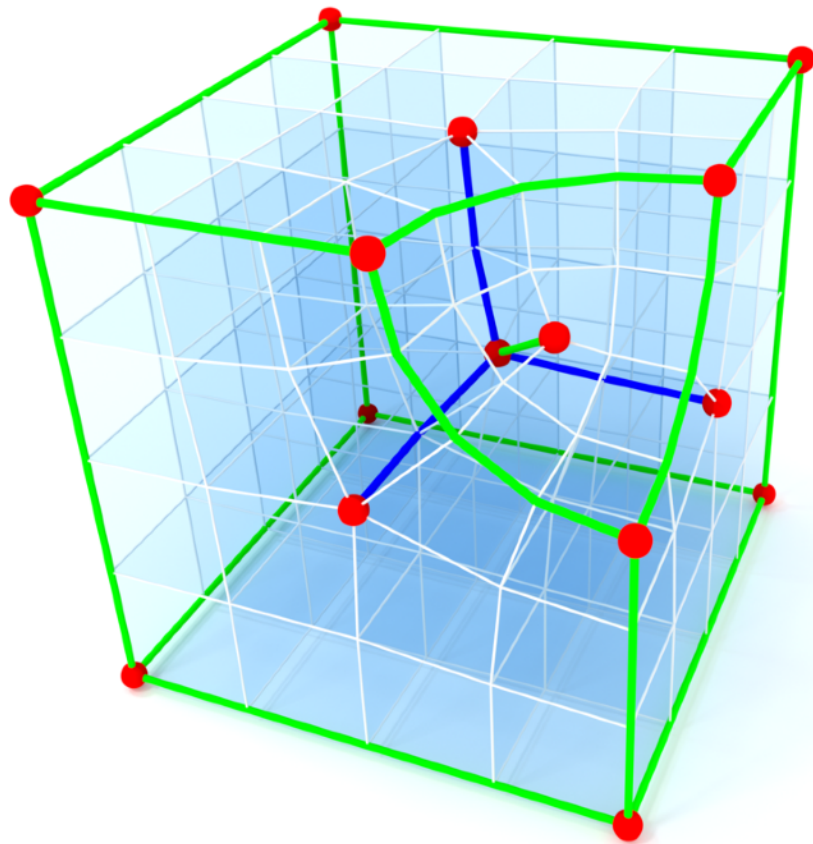
each singular node is one of the 11 configurations



# Hex Meshable Singularity Graphs (valence 3/4/5)

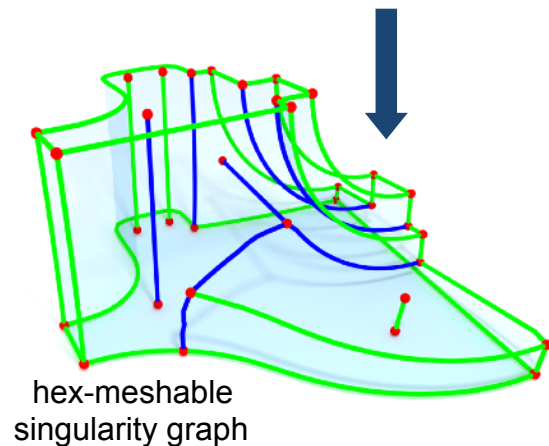
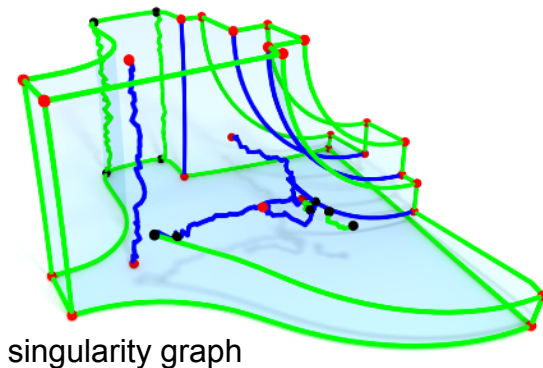
- **Global Necessary Condition**  
analog of discrete Poincaré-Hopf formula

$$\sum_{v \in \partial V_S} \frac{1}{2} \left( 1 - \frac{\text{val}_h(v)}{4} \right) - \sum_{e \in \partial E_S^-} \text{idx}(e) + \sum_{v \in \overset{\circ}{V}_S} \left( 1 - \frac{\text{val}_h(v)}{8} \right) - \sum_{e \in \overset{\circ}{E}_S^-} \text{idx}(e) = 0.$$

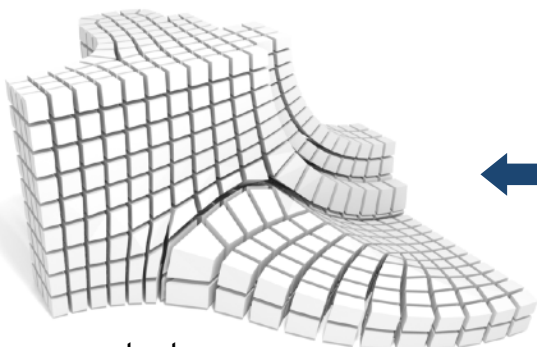
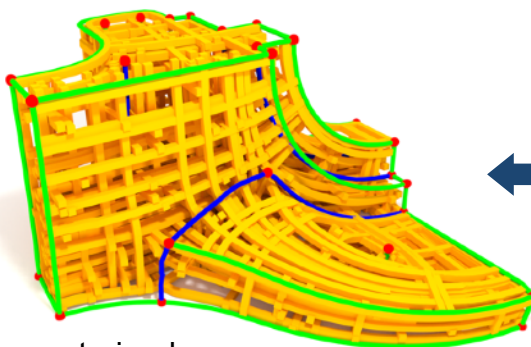
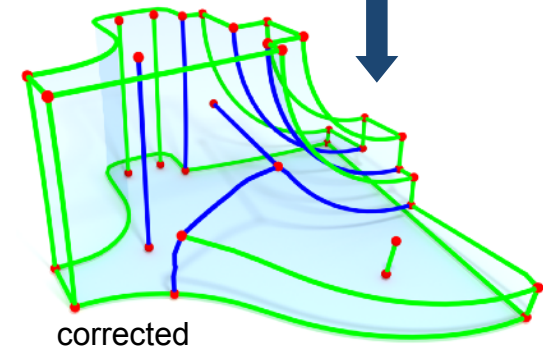
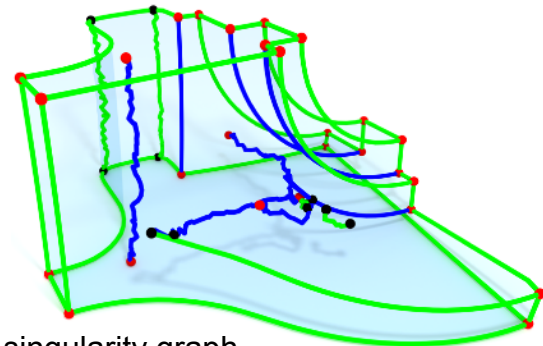
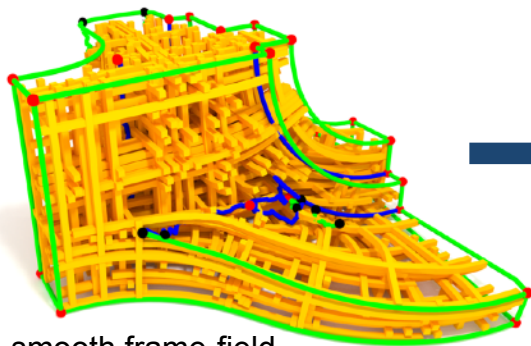
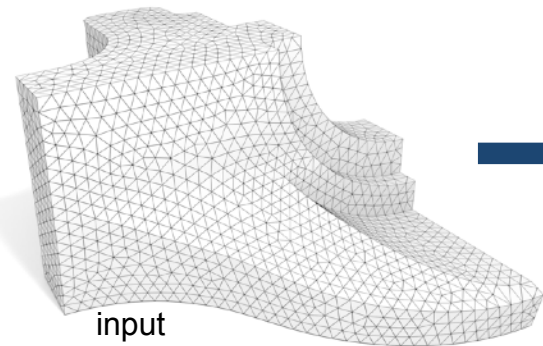


# Hex Meshable Singularity Graphs (valence 3/4/5)

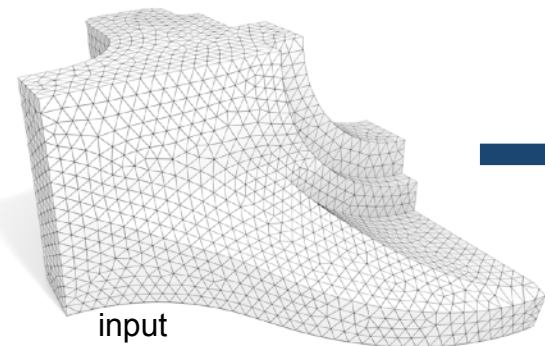
- **Necessary Conditions**  
many inconsistencies can be identified
- **Repairing Singularity Graph**  
open problem  
→ so far manually using above conditions
- **Conditions are not sufficient!**  
but algorithmic verification by constructing  
the corresponding frame-field



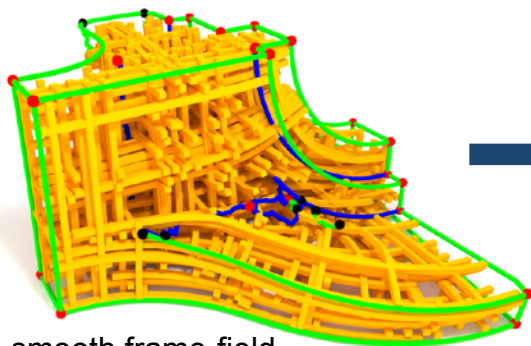
# Modified Algorithm



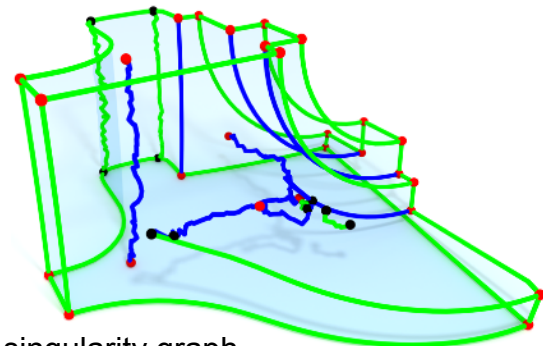
# Modified Algorithm



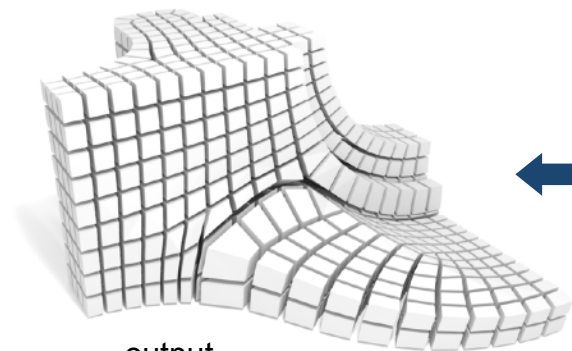
input  
tetrahedral mesh



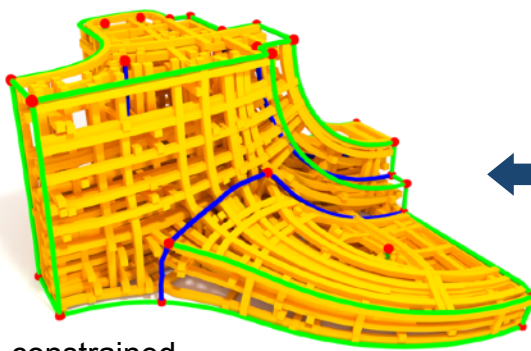
smooth frame-field



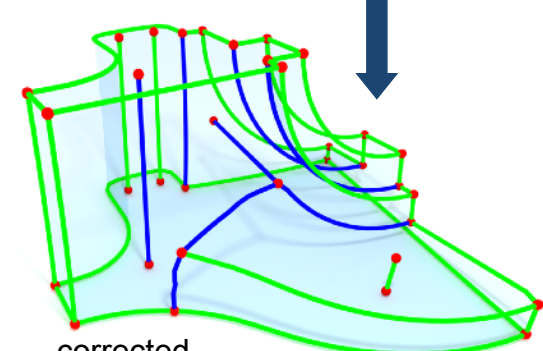
singularity graph



output  
hexahedral mesh



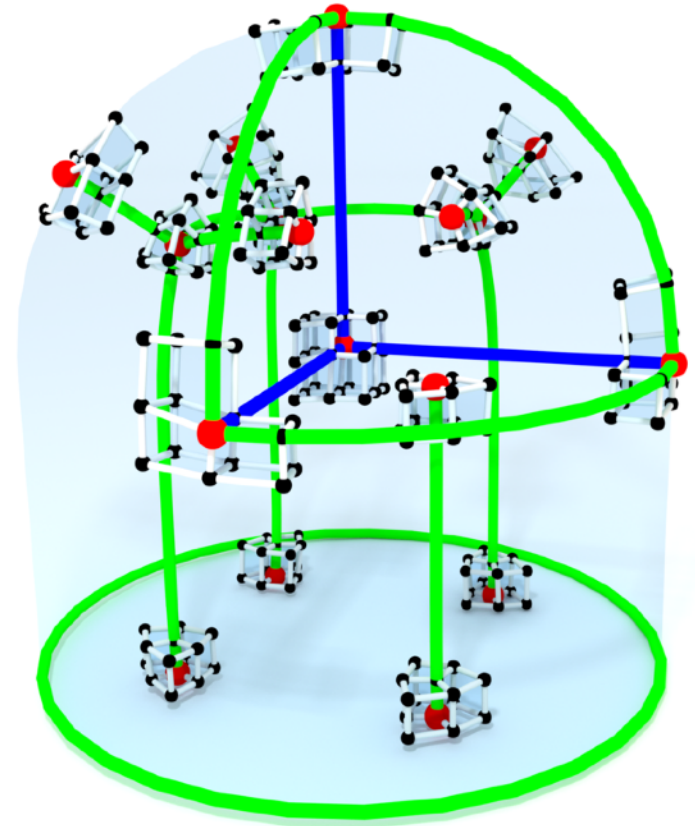
constrained  
frame-field



corrected  
singularity graph

# Algorithm: Constrained Frame-Fields

- **Input:**
  - Tetrahedral mesh
  - Singularity graph  $\mathcal{S} = (V_{\mathcal{S}}, E_{\mathcal{S}})$  satisfying
    - ➔ local necessary conditions
    - ➔ global necessary condition
- **Output:**
  - the smoothest discrete cross-field  $\mathcal{C}$  that is boundary-aligned and matches the singularity graph  $\mathcal{S}$



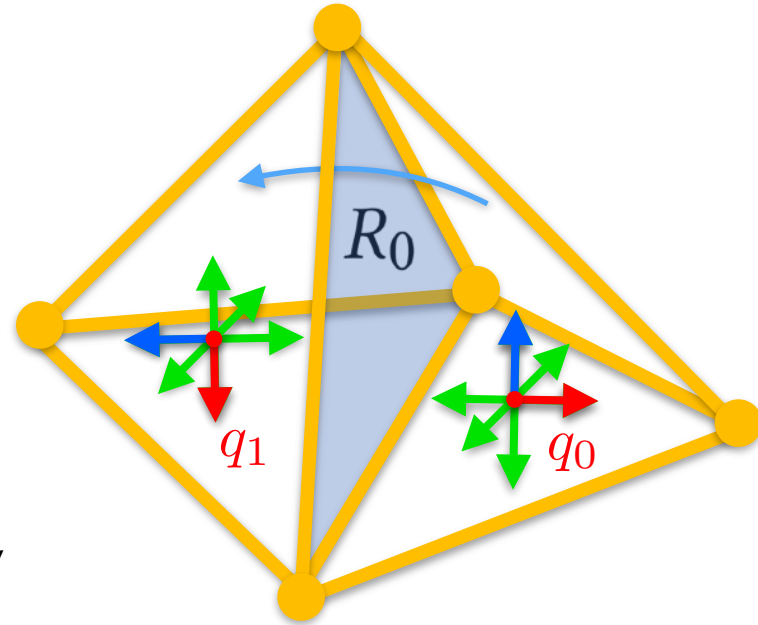
# Algorithm: Constrained Frame-Fields

- **Discrete Frame-Field Representation**

- one frame  $q_i$  per tet
- one matching  $R \in \text{Oct}$  per face
- 24 different matchings

- **Large Nonlinear Mixed-Integer Problem**

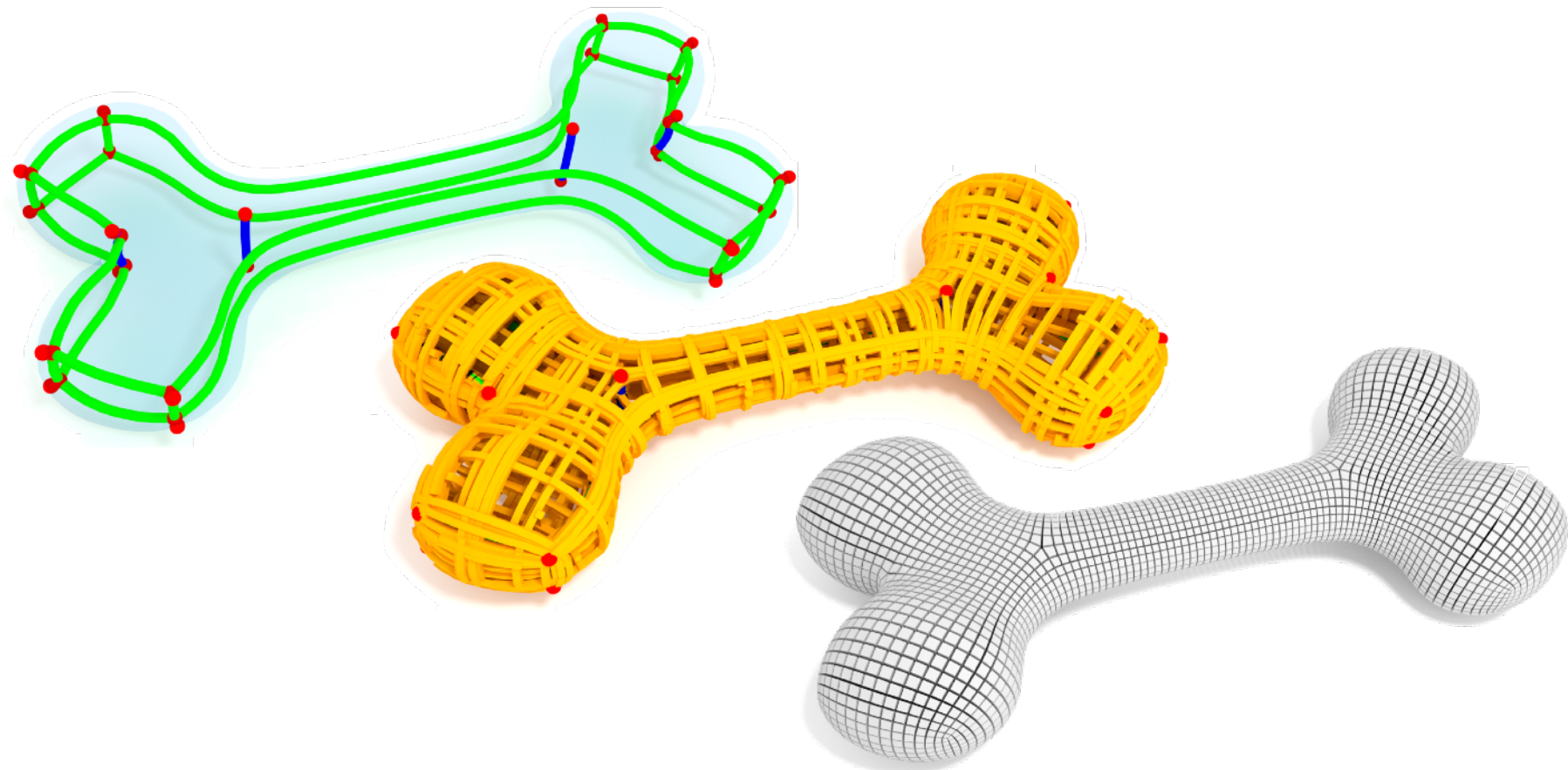
- singularities induce constraints on products of matching rotations
- solution of **discrete** matchings can be done independently of **continuous** frame DOFs
- fast solution possible through careful strategy
- ➔ chart-merging algorithm
- ➔ feasibility certifies **global consistency** of singularity graph



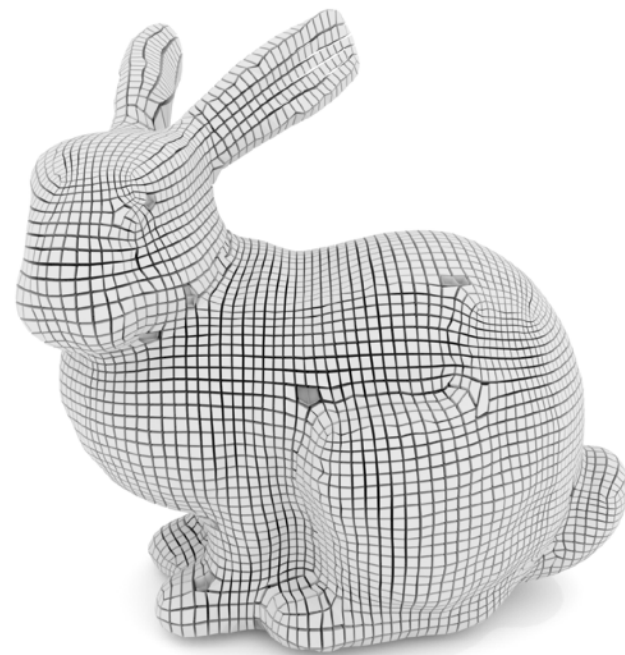
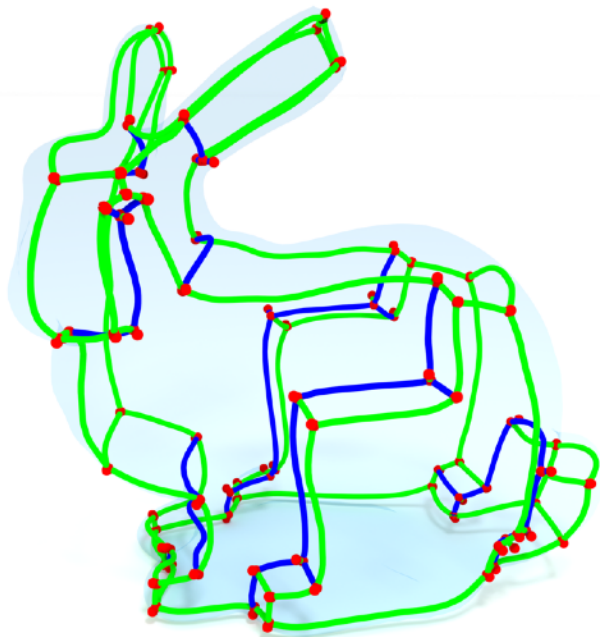


# Results

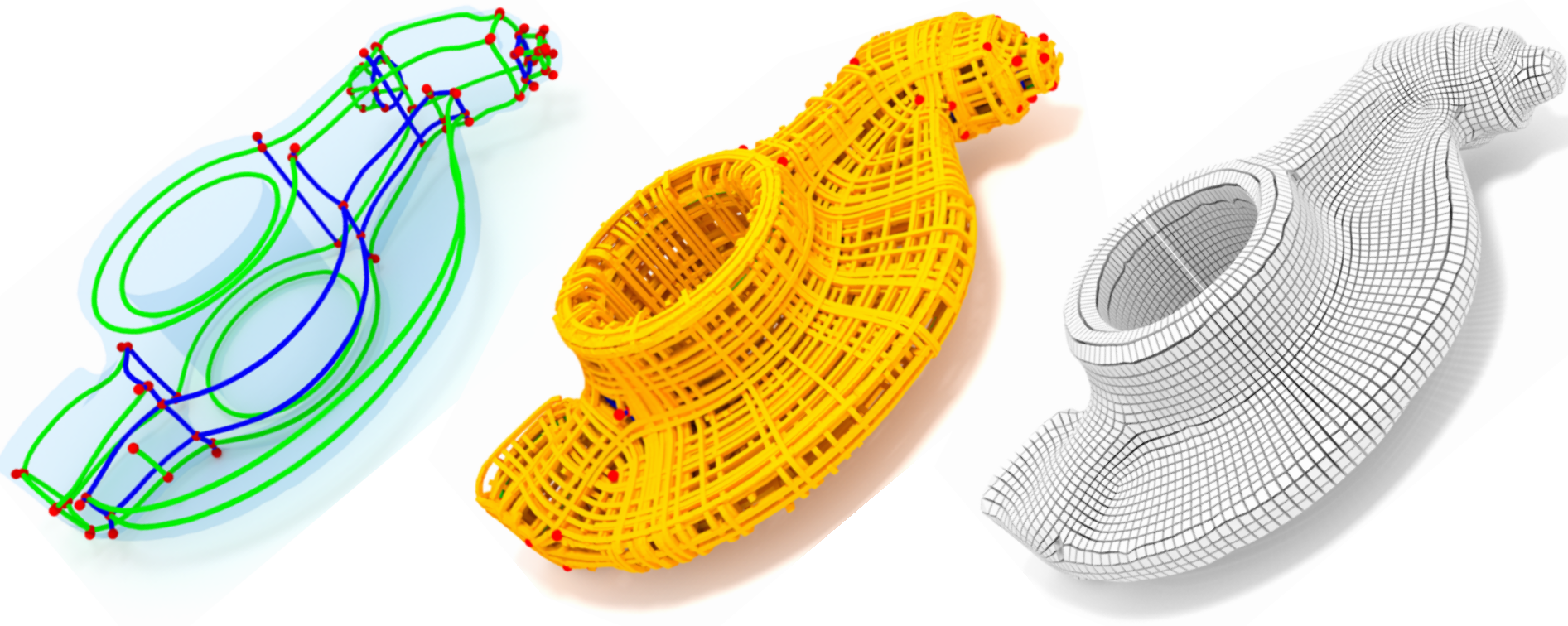
# Results — Bone [71K tets, 0.9s]



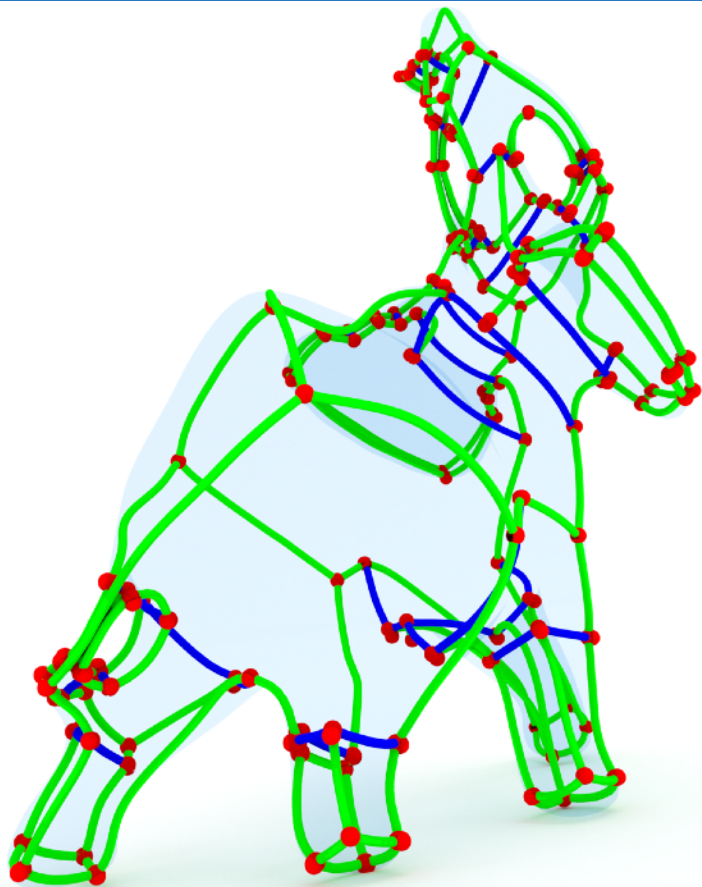
## Results — Bunny [130K tets, 2.7s]



# Results — Rockerarm [122K tets, 3.1s]



# Results — Elephant [300K tets, 9.9s]



# Integer-Grid Maps

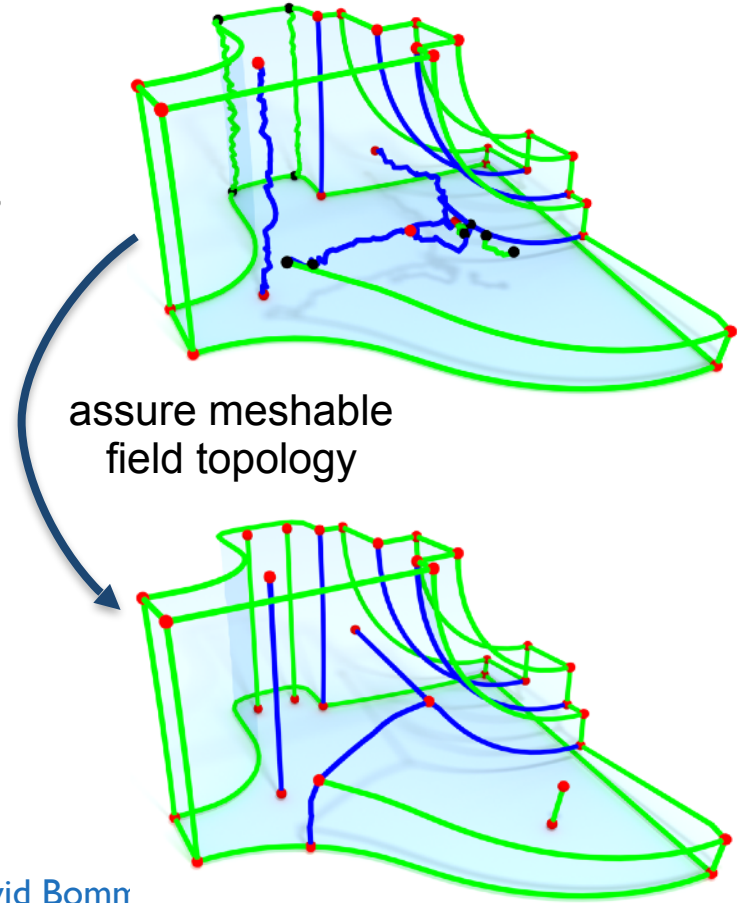
## Scientific Challenges

# Scientific Challenges

- SC1.** Frame-Field Topology
- SC2.** Volumetric Integer-Grid Maps
- SC3.** Precise Control
- SC4.** Quality
- SC5.** Scalability

# Scientific Challenges

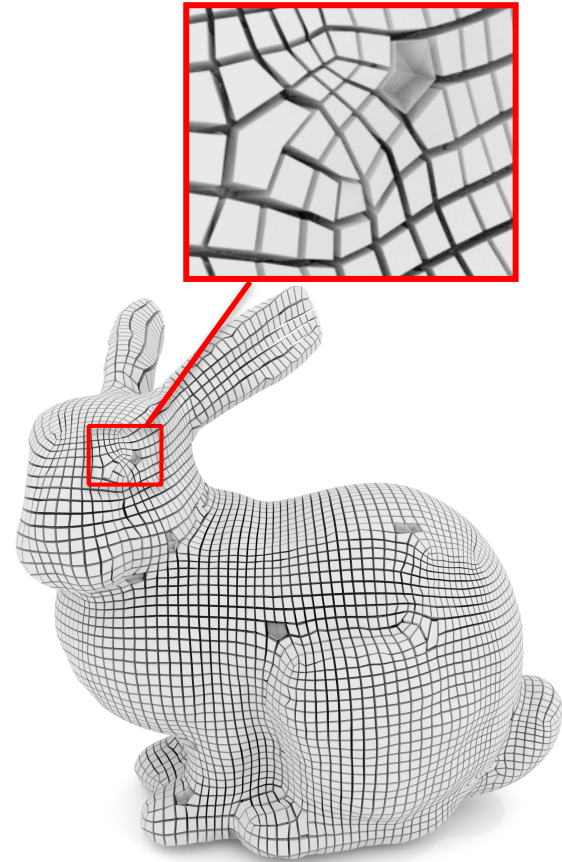
- SC1. Frame-Field Topology
- SC2. Volumetric Integer-Grid Maps
- SC3. Precise Control
- SC4. Quality
- SC5. Scalability





# Scientific Challenges

- SC1. Frame-Field Topology
- SC2. Volumetric Integer-Grid Maps
- SC3. Precise Control
- SC4. Quality
- SC5. Scalability



# Scientific Challenges

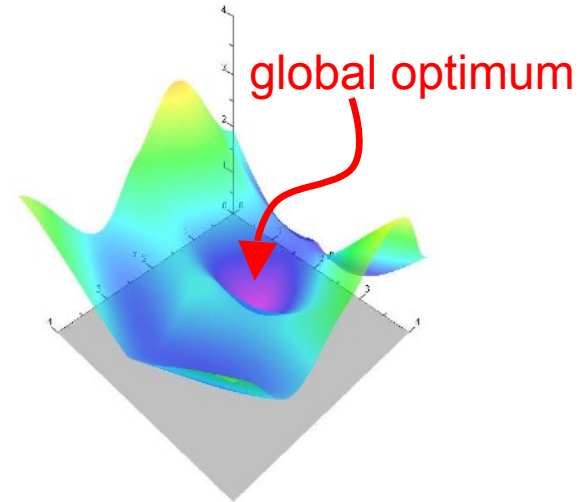
SC1. Frame-Field Topology

SC2. Volumetric Integer-Grid Maps

SC3. Precise Control  $\longrightarrow$  soft & hard constraints

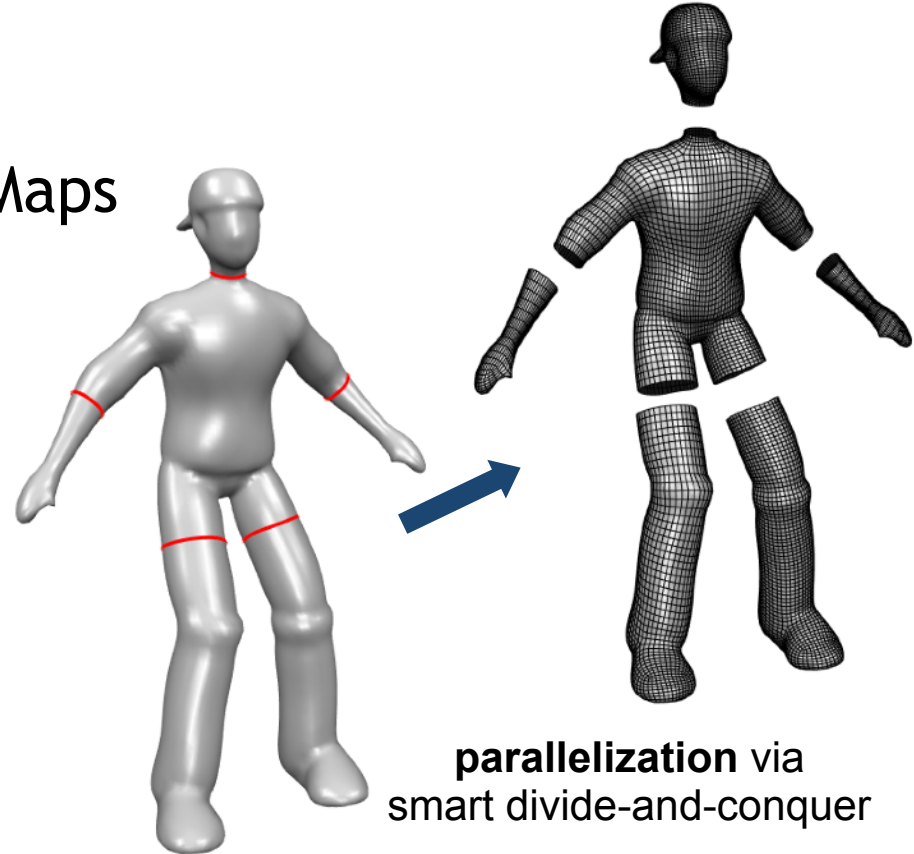
SC4. Quality  $\longrightarrow$  get close to global optimum

SC5. Scalability



# Scientific Challenges

- SC1. Frame-Field Topology
- SC2. Volumetric Integer-Grid Maps
- SC3. Precise Control
- SC4. Quality
- SC5. Scalability



**parallelization** via  
smart divide-and-conquer

# Summary & Outlook

- **Integer-Grid Maps**

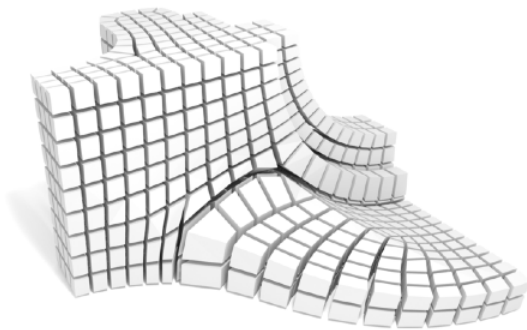
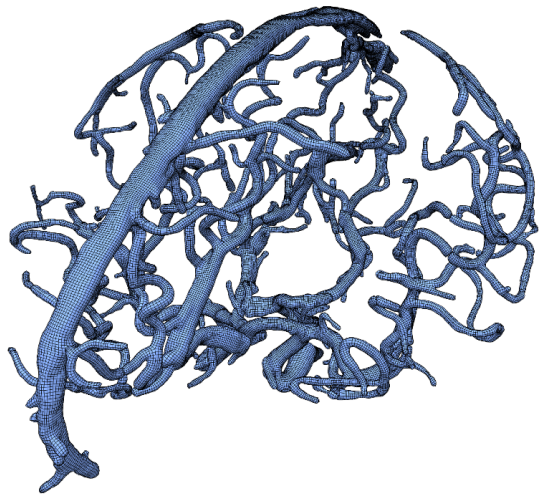
- offer good balance of quality criteria
- efficiency through frame-fields

- **Quadrilateral Meshing**

- robustness / performance / quality / control
- complete toolbox available

- **Hexahedral Meshing**

- significantly more challenging, many unsolved aspects, e.g. robustness
- **contribution 1**: local/global necessary conditions for meshable singularity graphs
- **contribution 2**: algorithm for singularity-constrained fields
- important next step towards robustness:
  - ➔ automatic correction of singularity graph



Thank You!

